MAD

Models & Algorithms for Distributed systems

-- 4/5 --

download slides at

http://people.rennes.inria.fr/Eric.Fabre/

Today...

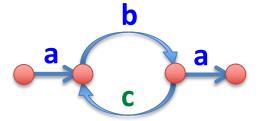
- Playing with networks of automata
- A recap of their algebraic properties
- Extra properties, enabling distributed computations
- Applications
 - distributed diagnosis
 - distributed planning

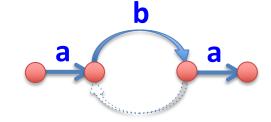
What do we have so far?

Projection operators

• on words and languages $\Pi_{\{a,b\}}$ (abcbcba) = abbba

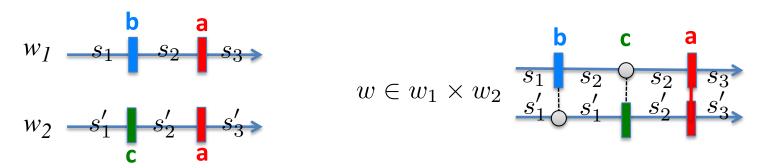
on automata





Thm
$$\Pi_{\Sigma'}[\mathcal{L}(\mathcal{A})] = \mathcal{L}[\Pi_{\Sigma'}(\mathcal{A})]$$

Product operators on languages and on automata



When 2 words w_1 , w_2 match on common letters, any word w in their product is also a word of the product automaton.

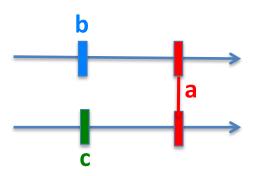
Thm
$$\mathcal{L}(\mathcal{A}_1 \times ... \times \mathcal{A}_N) = \mathcal{L}(\mathcal{A}_1) \times ... \times \mathcal{L}(\mathcal{A}_N)$$

Consequence: computations on languages (infinite objects) can be turned into computations on automata (finite objects)

Traces = runs seen as partial orders, equivalent to a product of local words they can thus be encoded/represented as tuples of (local) words

$$[w] = w_1 \times ... \times w_N$$
 where $w_i \in \Sigma_i^*$

multiple (equivalent) words concurrent events interleaved partial ordering not visible single tuple of words factored form of a trace : more compact partial order easily readable



Remark: $\forall w \in w_1 \times ... \times w_N$ one has $\Pi_i(w) = w_i$

More algebraic properties

Reduced languages

- a distributed/modular automaton $\mathcal{A} = \mathcal{A}_1 imes ... imes \mathcal{A}_N$
- one has $\mathcal{L}(\mathcal{A}_i)\subseteq \Sigma_i^*$ and $\mathcal{L}(\mathcal{A})=\mathcal{L}(\mathcal{A}_1) imes ... imes \mathcal{L}(\mathcal{A}_N)\subseteq \Sigma^*$
- by definition, one has $\mathcal{L}_i' = \Pi_i[\mathcal{L}(\mathcal{A})] \subseteq \mathcal{L}(\mathcal{A}_i)$
- these words represent behaviors of $\,A_i\,$ that remain possible once this component is connected to the rest of the system

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$$\mathcal{L}(\mathcal{A}) = \mathcal{L}(\mathcal{A}_1) \times ... \times \mathcal{L}(\mathcal{A}_N) \\ = \mathcal{L}_1' \times ... \times \mathcal{L}_N'$$
 minimal factored form

 $\begin{array}{l} \underline{\mathsf{Proof}} \colon \supseteq \text{ is obvious, so only } \subseteq \text{ must be proved} \\ \text{any word } w \in \mathcal{L}(\mathcal{A}) \quad \text{satisfies } w \in w_1 \times ... \times w_N \\ \text{for some } w_i \in \mathcal{L}(\mathcal{A}_i) \\ \text{and one has } w_i = \Pi_i(w) \quad \text{so } w_i \in \mathcal{L}_i' \end{array}$

$$L_1$$
 = {abb, ababa, baba} L_2 = {cc, cac, aca} L_1 = {abb, baba} L_2 = {cac, aca} L_2 = {cac, aca} L_2 = {cac, aca} L_2 = $L_1 \times L_2$ = $L_1 \times L_2$ = {cabbc, cabb, babca, bacba}

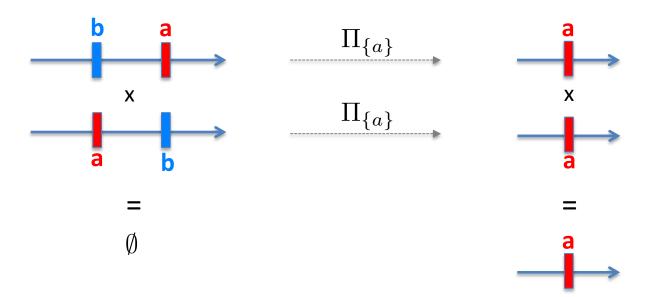
Objective

- given the distributed automaton $\mathcal{A} = \mathcal{A}_1 imes ... imes \mathcal{A}_N$
- we want to compute the reduced languages $\,\mathcal{L}_i'\,=\,\Pi_i[\mathcal{L}(\mathcal{A})]\,\subseteq\,\mathcal{L}(\mathcal{A}_i)\,$
- without computing A nor L(A) which are huge objects
- Interest
 - check system design more easily (deadlocks/liveness, reachability, safety...)
 - eliminate spurious behaviors, debugging
 - select runs that match some property (e.g. use in diagnosis and planning)

A central property

Thm let
$$\mathcal{L}_i \subseteq \Sigma_i^*$$
, i=1,2, let $\Sigma' \subseteq \Sigma$ if $\Sigma' \supseteq \Sigma_1 \cap \Sigma_2$ then
$$\Pi_{\Sigma'}(\mathcal{L}_1 \times \mathcal{L}_2) = \Pi_{\Sigma'}(\mathcal{L}_1) \times \Pi_{\Sigma'}(\mathcal{L}_2)$$

- **Proof** : exercise, by double inclusion ; assume first that $\Sigma' = \Sigma_1 \cap \Sigma_2$
- necessity of $\Sigma' \supseteq \Sigma_1 \cap \Sigma_2$

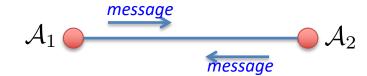


Consequence 1

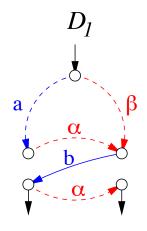
Cor : take
$$\Sigma'=\Sigma_1\supseteq\Sigma_1\cap\Sigma_2$$
, one has
$$\Pi_{\Sigma_1}(\mathcal{L}_1\times\mathcal{L}_2)\ =\ \mathcal{L}_1\times\Pi_{\Sigma_1\cap\Sigma_2}(\mathcal{L}_2)$$

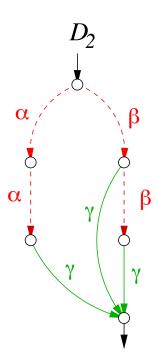
$$\begin{array}{ll} \textbf{Consequence} & \mathcal{L}_1' = \Pi_{\Sigma_1}[\mathcal{L}(\mathcal{A})] = \Pi_{\Sigma_1}[\mathcal{L}(\mathcal{A}_1 \times \mathcal{A}_2)] \\ & = \Pi_{\Sigma_1}[\mathcal{L}(\mathcal{A}_1) \times \mathcal{L}(\mathcal{A}_2)] \\ & = \mathcal{L}(\mathcal{A}_1) \times \Pi_{\Sigma_1 \cap \Sigma_2}[\mathcal{L}(\mathcal{A}_2)] \\ & = \mathcal{L}(\mathcal{L}(\mathcal{A}_1) \times \Pi_{\Sigma_1 \cap \Sigma_2}[\mathcal{L}(\mathcal{A}_2)] \\ & = \mathcal{L}(\mathcal{L}(\mathcal{A}_1) \times \Pi_{\Sigma_1 \cap \Sigma_2}[\mathcal{L}(\mathcal{$$

- the reduced language of A₁ combines its local language with a message from the other component A₂
- the message contains information about possible actions of A₂ on shared letters
- these synchronization possibilities are used to filter out behaviors of A₁ that are not compatible with any run of A₂

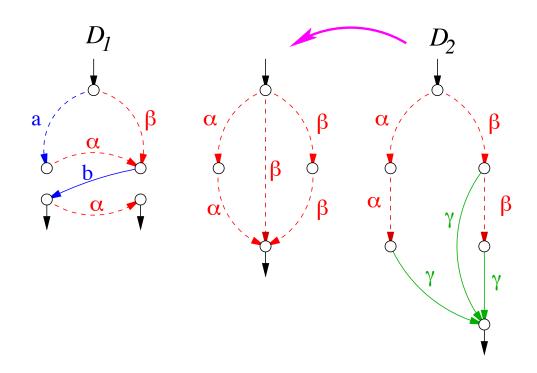


- $\Sigma_1 = \{a, b, \alpha, \beta\}, \quad \Sigma_2 = \{\alpha, \beta, \gamma\}$
- computations performed on automata instead of languages

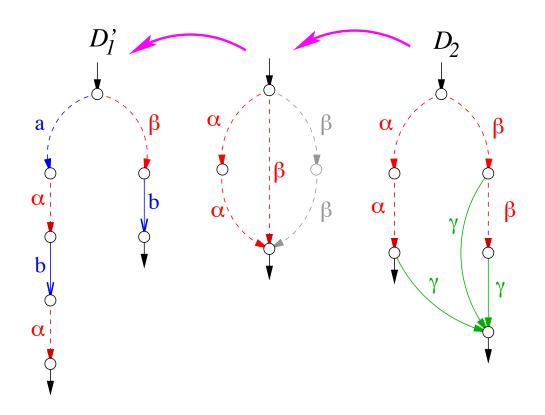




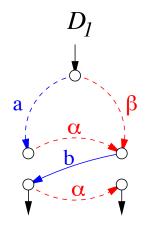
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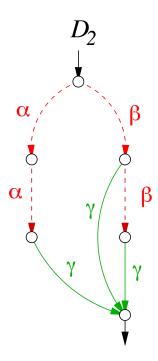


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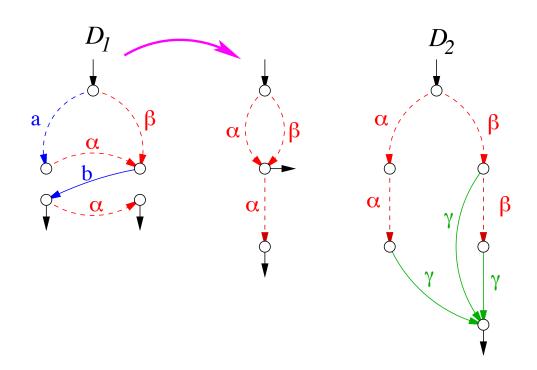


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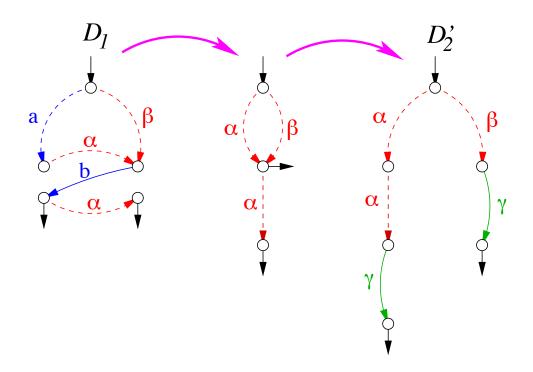




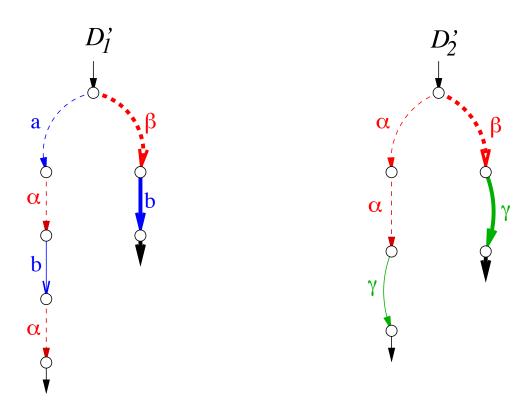
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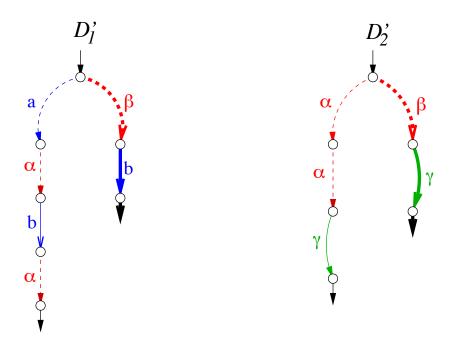


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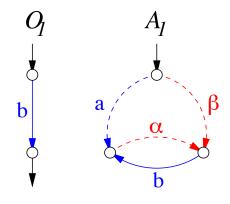
Distributed planning

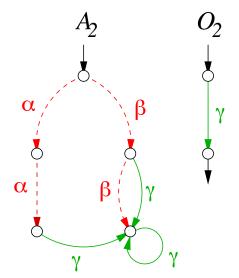
- compute a pair/tuple of compatible words/runs/sequences of actions, one per component
- computations are distributed, by message passing
- the resulting global plan is a tuple of local plans, i.e. a Mazurkiewicz trace,
 i.e. a partial order of actions, where actors sync. by rendez-vous
- the resulting plan can be executed in a distributed manner



Distributed diagnosis

- some actions are observable in each component : $\; \Sigma_{i,o} \subseteq \Sigma_i \;$
- the global system $A = A_1 \times ... \times A_N$ performs some hidden run wone only observes its signature in each component
- compute a pair/tuple of compatible words/runs/sequences of actions, one per component $o_i = \prod_{\Sigma_{i,o}}(w)$
- objective = recover all global runs matching distributed observations $o_1, \, \ldots \, , \, o_N$





$$\Sigma_{1,o} = \{b\} \subseteq \{a, b, \alpha, \beta\} = \Sigma_1$$
 $\Sigma_{2,o} = \{\gamma\} \subseteq \{\alpha, \beta, \gamma\} = \Sigma_2$

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Method

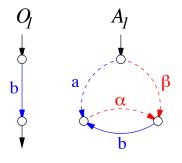
- synchronize runs of the distributed system with distributed observations
- observe that observations are a partial order, as well as runs of the system (they are handled in factorized form)
- idea: compute local diagnoses, then reduce them!

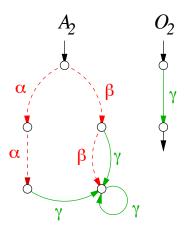
$$\mathcal{D} = \mathcal{L}(\mathcal{A}_1 \times \mathcal{A}_2) \times (o_1 \times o_2)$$

$$= [\mathcal{L}(\mathcal{A}_1) \times o_1] \times [\mathcal{L}(\mathcal{A}_2) \times o_2]$$

$$= \mathcal{D}_1 \times \mathcal{D}_2$$

$$= \mathcal{D}_1' \times \mathcal{D}_2'$$





Method

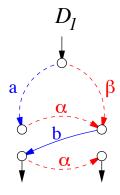
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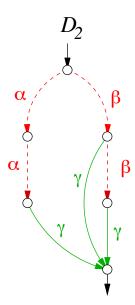
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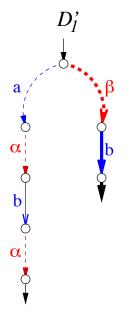
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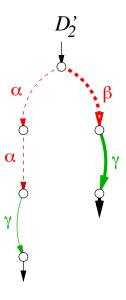
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$$= \mathcal{D}_1 \times \mathcal{D}_2$$

$$= \mathcal{D}_1' \times \mathcal{D}_2'$$





Consequence 2

$$\Sigma' \supseteq \Sigma_1 \cap \Sigma_2 \quad \Rightarrow \quad \Pi_{\Sigma'}(\mathcal{L}_1 \times \mathcal{L}_2) \quad = \quad \Pi_{\Sigma'}(\mathcal{L}_1) \times \Pi_{\Sigma'}(\mathcal{L}_2)$$



Case of 3 components, with $\Sigma_1 \cap \Sigma_3 \subseteq \Sigma_2$ (or even $\Sigma_1 \cap \Sigma_3 = \emptyset$)

Merge rule :

$$\mathcal{L}_{2}' = \Pi_{\Sigma_{2}}[\mathcal{L}(\mathcal{A})] = \Pi_{\Sigma_{2}}[\mathcal{L}(\mathcal{A}_{1}) \times \mathcal{L}(\mathcal{A}_{2}) \times \mathcal{L}(\mathcal{A}_{3})]$$

$$= \mathcal{L}(\mathcal{A}_{2}) \times \Pi_{\Sigma_{2}}[\mathcal{L}(\mathcal{A}_{1}) \times \mathcal{L}(\mathcal{A}_{3})]$$

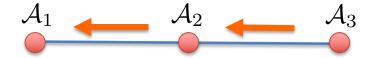
$$= \mathcal{L}(\mathcal{A}_{2}) \times \Pi_{\Sigma_{2}}[\mathcal{L}(\mathcal{A}_{1})] \times \Pi_{\Sigma_{2}}[\mathcal{L}(\mathcal{A}_{3})]$$

$$= \mathcal{L}(\mathcal{A}_{2}) \times \Pi_{\Sigma_{1} \cap \Sigma_{2}}[\mathcal{L}(\mathcal{A}_{1})] \times \Pi_{\Sigma_{2} \cap \Sigma_{3}}[\mathcal{L}(\mathcal{A}_{3})]$$

- combines messages of lateral components with local language
- messages inform about possible words on shared letters

Consequence 2

$$\Sigma' \supseteq \Sigma_1 \cap \Sigma_2 \quad \Rightarrow \quad \Pi_{\Sigma'}(\mathcal{L}_1 \times \mathcal{L}_2) \quad = \quad \Pi_{\Sigma'}(\mathcal{L}_1) \times \Pi_{\Sigma'}(\mathcal{L}_2)$$



Case of 3 components, with $\Sigma_1 \cap \Sigma_3 \subseteq \Sigma_2$ (or even $\Sigma_1 \cap \Sigma_3 = \emptyset$)

• Propagation rule : uses $(\Sigma_1 \cup \Sigma_2) \cap (\Sigma_2 \cup \Sigma_3) = \Sigma_2$

$$\mathcal{L}'_{1} = \Pi_{\Sigma_{1}}[\mathcal{L}(\mathcal{A})] = \Pi_{\Sigma_{1}}[\mathcal{L}(\mathcal{A}_{1}) \times \mathcal{L}(\mathcal{A}_{2}) \times \mathcal{L}(\mathcal{A}_{3})]$$

$$= \mathcal{L}(\mathcal{A}_{1}) \times \Pi_{\Sigma_{1}}[\mathcal{L}(\mathcal{A}_{2}) \times \mathcal{L}(\mathcal{A}_{3})]$$

$$= \mathcal{L}(\mathcal{A}_{1}) \times \Pi_{\Sigma_{1}}[\Pi_{\Sigma_{1} \cup \Sigma_{2}}[\mathcal{L}(\mathcal{A}_{2}) \times \mathcal{L}(\mathcal{A}_{3})]]$$

$$= \mathcal{L}(\mathcal{A}_{1}) \times \Pi_{\Sigma_{1}}[\Pi_{\Sigma_{2}}[\mathcal{L}(\mathcal{A}_{2}) \times \mathcal{L}(\mathcal{A}_{3})]]$$

$$= \mathcal{L}(\mathcal{A}_{1}) \times \Pi_{\Sigma_{1} \cap \Sigma_{2}}[\mathcal{L}(\mathcal{A}_{2}) \times \Pi_{\Sigma_{2}}[\mathcal{L}(\mathcal{A}_{3})]]$$

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- messages propagate from extremities
- they are progressively combined to local component, reduced and forwarded

Take home messages

Computing on runs of a distributed system

- should be done on the factorized form (captures concurrency, more compact)
- this can be done in a distributed/modular way, by message passing

Next time

- Petri nets: a new model for distributed/concurrent systems
- unfoldings/event structures: a new representation for (sets of) runs in a true concurrency semantics