

# Fault diagnosis for Probabilistic Systems a semantical and algorithmic journey

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based on joint work with Éric Fabre, Stefan Haar, Serge Haddad,  
Loïc Hélouët and Engel Lefaucheux

# Two tales of smoke and observation



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Diagnosis, non-interference, information flow, opacity, etc.

# Outline

Introduction to fault diagnosis

Diagnosability in probabilistic systems

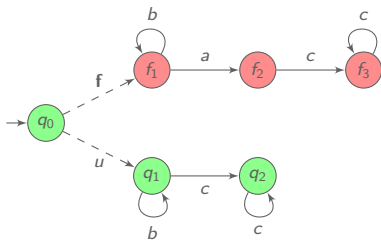
- Exact Diagnosis

- Approximate diagnosis

Control for probabilistic diagnosability

Conclusion

**Objective:** tell whether a fault occurred, based on observations.

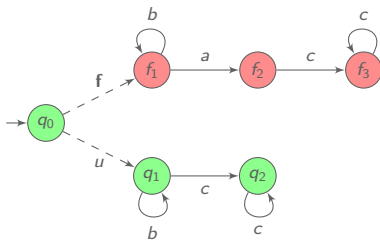


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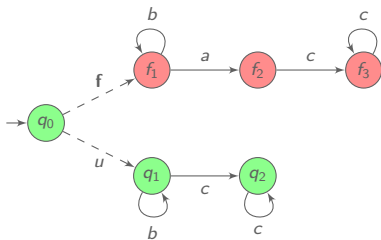
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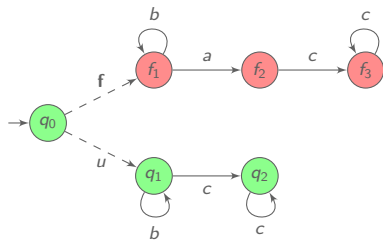
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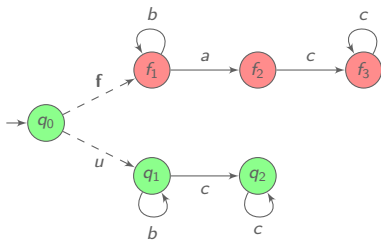
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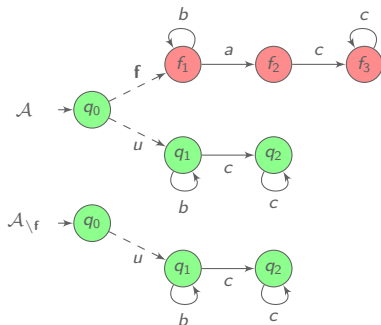
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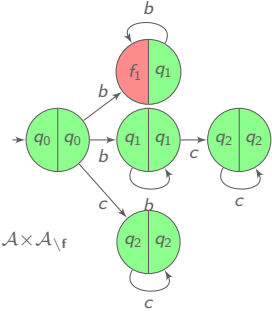
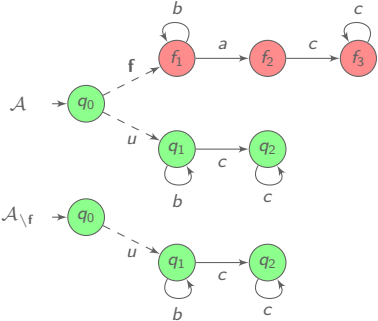
Remark: w.l.o.g. state space partitioned into correct and faulty states

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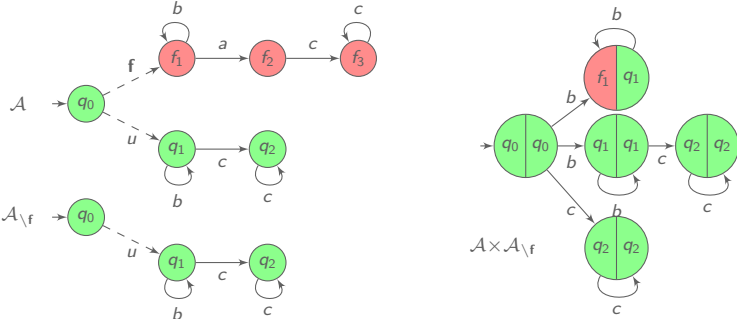
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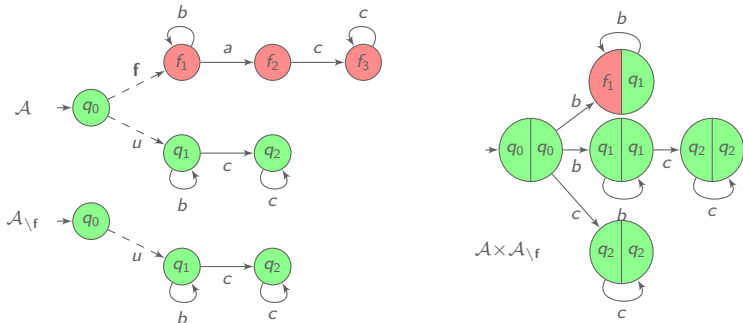
# Deciding diagnosability in discrete event systems



indeterminate cycle:  $(f_0, q_0) \cdots \rightarrow (f_n, q_n) \rightarrow (f_0, q_0)$  s.t.  $f_i$  **faulty** and  $q_i$  **correct**

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**Decidability and complexity of diagnosability**  
Diagnosability is decidable in PTIME.

[JHCK01]

# Diagnosers

**Diagnoser:** assigns verdicts to observed sequences  $D : \Sigma_o^* \rightarrow \{\checkmark, \times, ?\}$

## Diagnoser requirements

- ▶ **Soundness:** if a fault is claimed  $\times$ , a fault occurred.
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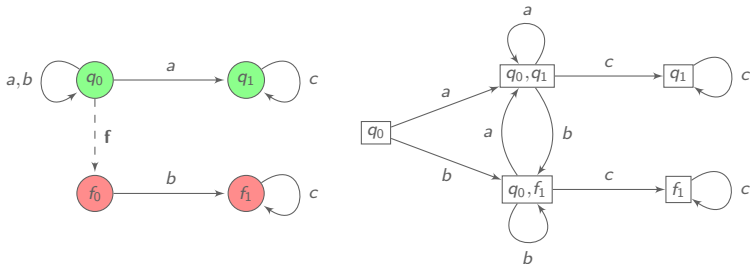
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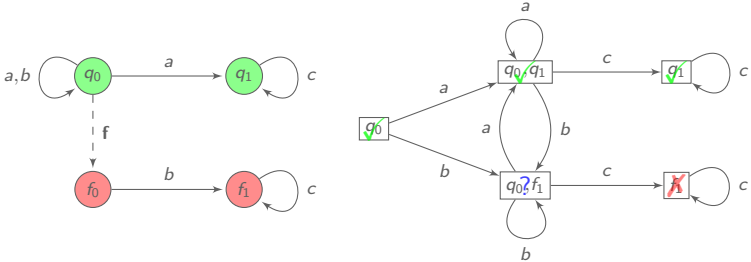
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# Diagnoser synthesis

## Complexity of diagnoser synthesis

Diagnoser synthesis is in EXPTIME.

**intuition:** subset construction to track possible correct and faulty states

[JHCK01] Jiang, Huang, Chandra and Kumar, *A polynomial algorithm for testing diagnosability of discrete-event systems*, TAC, 2001.

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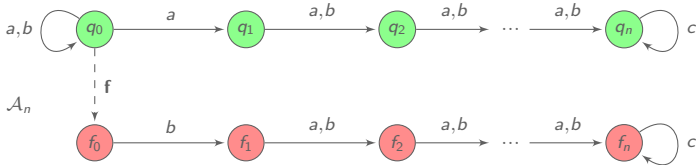
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There is a family ( $\mathcal{A}_n$ ) of diagnosable systems such that  $\mathcal{A}_n$  has  $2n + 2$  states and any diagnoser needs  $2^n$  states.



diagnoser must remember the last  $n$  events:  $2^n$  possibilities

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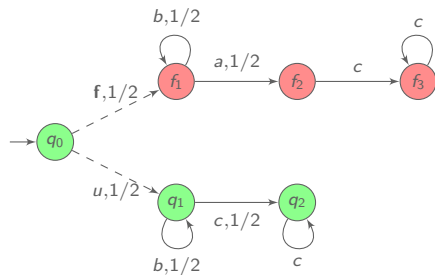
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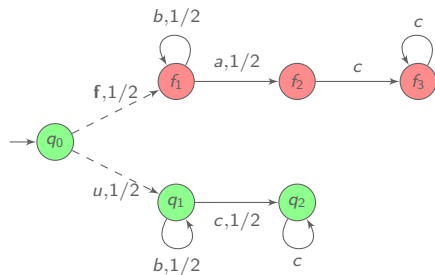
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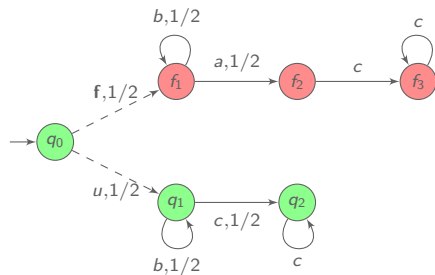


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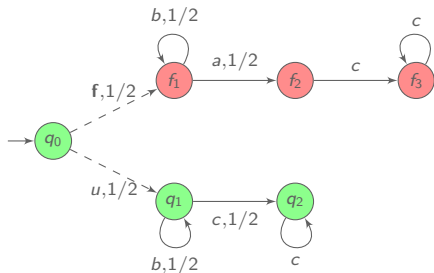


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How to adapt the framework to probabilistic systems?

- ▶ diagnosability notion(s)
- ▶ soundness and correctness for diagnosers
- ▶ algorithms for diagnosability checking and diagnoser synthesis

[TT05] Thorsley and Teneketzis, *Diagnosability of stochastic discrete-event systems*, TAC, 2005.

[CK13] Chen and Kumar, *Polynomial test for stochastic diagnosability of discrete-event systems*, TASE, 2013.

[BHL14] B., Haddad and Lefaucheux, *Foundation of diagnosis and predictability in probabilistic systems*, FSTTCS'14.

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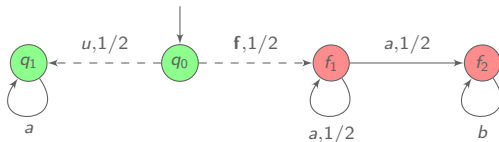
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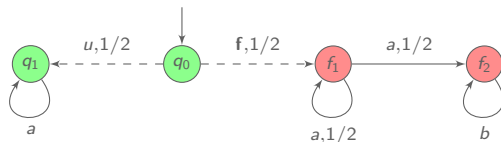


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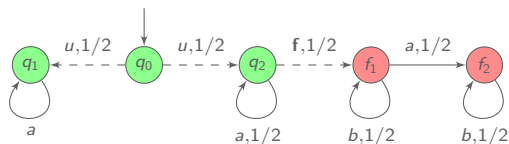
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2. Consider infinite observed sequences or their finite prefixes?



Infinite sequence  $a^\omega$  is surely correct.  
For every  $N$ ,  $a^N$  is ambiguous, and has probability greater than  $\frac{1}{2}$ .

# Four diagnosability specifications

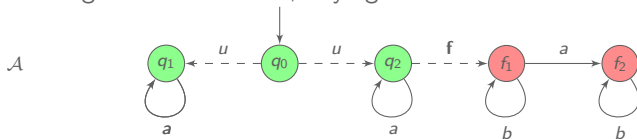
| Diagnosability     | All runs |                                   | Faulty runs |
|--------------------|----------|-----------------------------------|-------------|
| Finite prefixes    | FA       | $\Rightarrow$<br>$\not\Leftarrow$ | FF          |
| Infinite sequences | IA       | $\Rightarrow$<br>$\not\Leftarrow$ | IF          |

\* assuming finitely-branching models

# Characterizing diagnosability

e.g. FA-diagnosability

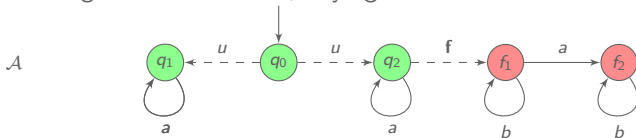
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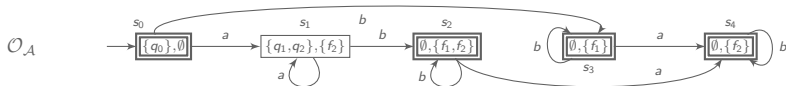
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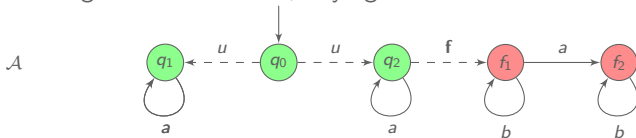




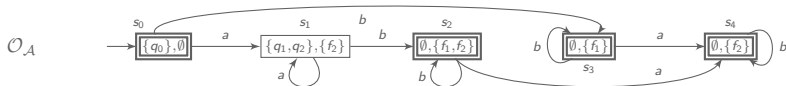
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$\mathcal{A}$  is not FA-diagnosable iff  
 there exists a BSCC of  $\mathcal{A} \times \mathcal{O}_{\mathcal{A}}$  where every state  $(q, C, F)$  satisfies  
 $q$  faulty and  $C \neq \emptyset$  or  $q$  correct and  $F \neq \emptyset$ .

[BHL14] B., Haddad and Lefauchaux, *Foundation of diagnosis and predictability in probabilistic systems*, FSTTCS'14.

# Solving diagnosability

Methodology to decide all diagnosability notions for probabilistic systems:

- ▶ build a deterministic observer  $\mathcal{O}_{\mathcal{A}}$  by an *ad hoc* subset construction
- ▶ form the product  $\mathcal{A} \times \mathcal{O}_{\mathcal{A}}$  to recover probabilistic behaviour
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Diagnosability is PSPACE-complete for probabilistic systems. [BHL14]

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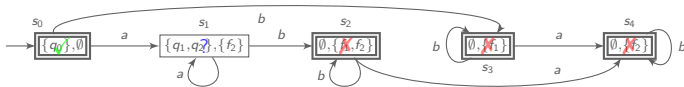
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Diagnoser derived from observer  $\mathcal{O}_{\mathcal{A}}$ :



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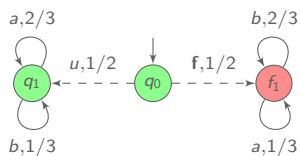
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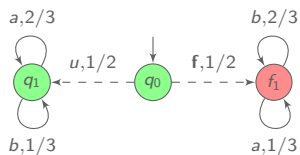
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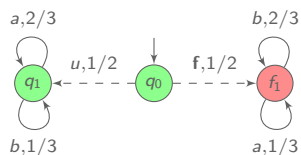


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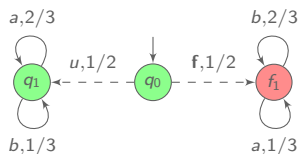
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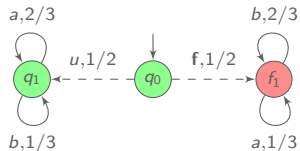
**Relaxed soundness:** if a fault is claimed, the probability of error is small.

[TT05] Thorsley and Teneketzis, *Diagnosability of stochastic discrete-event systems*, TAC, 2005.

# Formalisation of accurate approximate diagnosability

**Correcness proportion** of an observation sequence  $\sigma$

$$\text{CorP}(\sigma) = \frac{\mathbb{P}(\{\pi^{-1}(\sigma) \cap \text{correct}\})}{\mathbb{P}(\{\pi^{-1}(\sigma)\})}$$

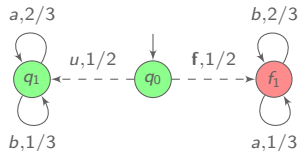


$$\text{CorP}(a) = 2/3,$$

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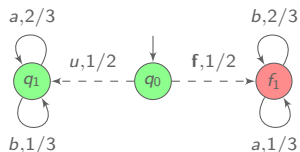


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# Accurate approximate diagnosers

## $\varepsilon$ -Diagnoser requirements

- ▶ **Soundness:** if a fault is claimed after  $\sigma$ , then  $\text{CorP}(\sigma) \leq \varepsilon$ .
- ▶ **Reactivity:** almost surely verdict  $\times$  is emitted after a fault.

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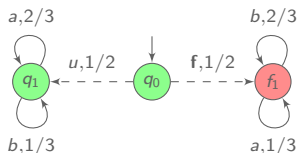
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admits  $\epsilon$ -diagnoser, for every  $\epsilon > 0$   
has no uniform  $\epsilon$ -diagnoser, for any  $\epsilon > 0$

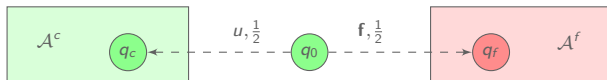
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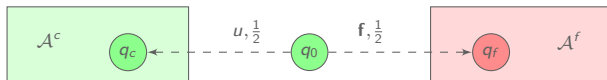


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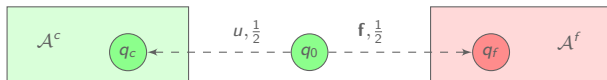
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- ▶ General case: polynomially many distance 1 tests.

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- ▶ Simple case: initial-fault models



$\mathcal{A}$  is accurate approximate diagnosable iff  $\text{dist}(\mathcal{A}^c, \mathcal{A}^f) = 1$   
i.e. there exists an event  $E \subseteq \Sigma_o^\omega$  s.t.  $|\mathbb{P}_{\mathcal{A}^c}(E) - \mathbb{P}_{\mathcal{A}^f}(E)| = 1$

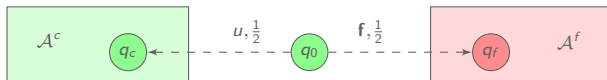
- ▶ General case: polynomially many distance 1 tests.
- ▶ Distance 1 is decidable in PTIME.

[CK14]

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[CK14]

Uniform accurate approximate diagnosability is undecidable. [BHL16]

[CK14] Chen and Kiefer, *On the Total Variation Distance of Labelled Markov Chains*, CSL-LICS'14.

[BHL16] B., Haddad and Lefaucheu, *Accurate approximate diagnosability of stochastic systems*, LATA'16.

# Outline

Introduction to fault diagnosis

Diagnosability in probabilistic systems

- Exact Diagnosis

- Approximate diagnosis

Control for probabilistic diagnosability

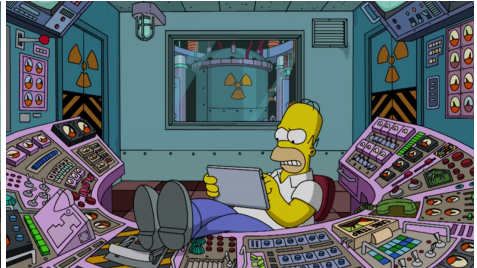
Conclusion

# From passive to active diagnosis





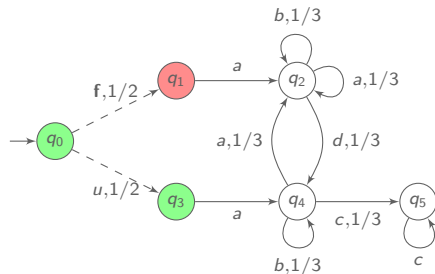
# From passive to active diagnosis



Original idea by Stefan Schwoon

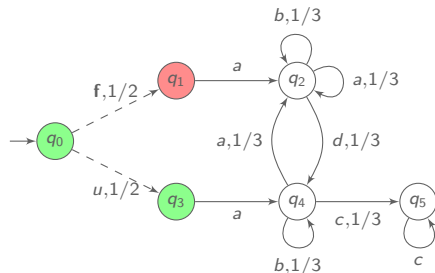
# Active probabilistic diagnosis

**Objective:** control the probabilistic system so that it is diagnosable



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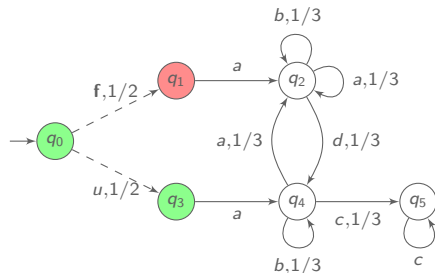
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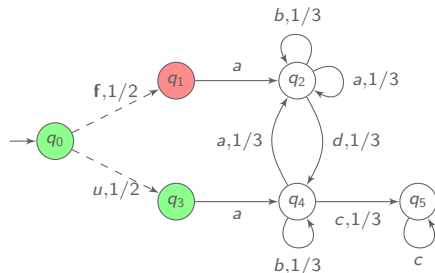


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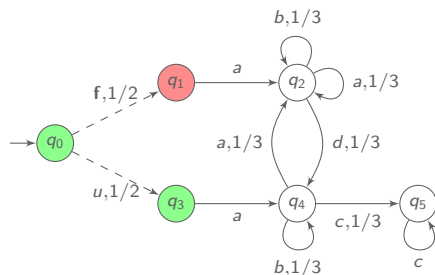


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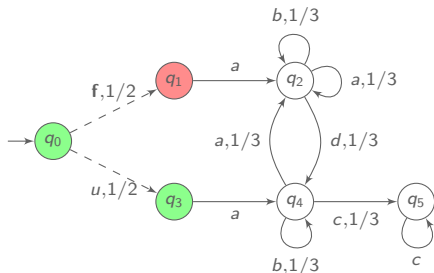
**Active probabilistic diagnosis problem**

[BFHHH14]

does there exist a controller such that the system is almost-surely diagnosable?

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The active probabilistic diagnosis problem is **EXPTIME-complete**.

[BFHHH14] B., Fabre, Haar, Haddad and H elou et, *Active diagnosis for probabilistic systems*, FoSSaCS'14.

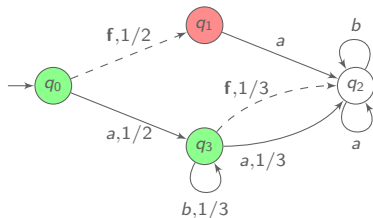
# Safe active probabilistic diagnosis

**Objective:** avoid fault-provocative controllers



# Safe active probabilistic diagnosis

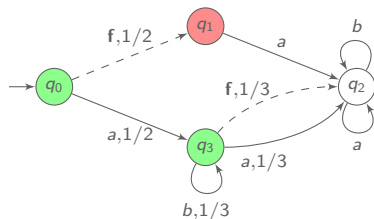
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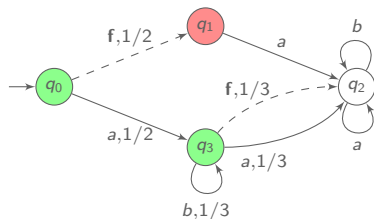
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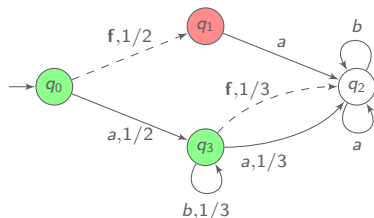
## Safe active probabilistic diagnosis

[BFHHH14]

does there exist a controller such that the system is almost-surely diagnosable **and** correct runs have positive probability?

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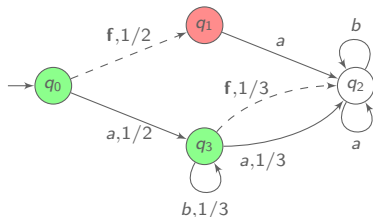
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The safe active probabilistic diagnosis problem is **undecidable**.

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The safe active probabilistic diagnosis problem is **undecidable**.

The safe active probabilistic diagnosis problem restricted to **finite memory controllers** is **EXPTIME-complete**.

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# Concluding remarks

**Contributions:** Foundations of stochastic diagnosis

- ▶ Investigation of semantical issues
- ▶ Exact diagnosis: tight complexity bounds for diagnosability and diagnoser synthesis problems
- ▶ Accurate approximate diagnosis: PTIME algorithm
- ▶ Active diagnosability

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**Perspectives:** Towards more quantitative questions

- ▶ Bounded-delay diagnosis  
tradeoff: delay vs diagnosability precision
- ▶ Space and time optimisation of observations  
tradeoff: observation cost vs diagnosability probability
- ▶ Challenge: control, partial observation, quantitative properties