



Efficient Dynamic Reconfiguration for Multi-Context Embedded FPGA

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Abstract

Dynamic reconfiguration on fine-grained architecture can only be reached by multi-context FPGAs when reconfiguration time is a critical issue. Unfortunately the multiple contexts bring power and area overhead. This paper introduces the Dynamic Unifier and reConfigurable blocK (DUCK), a new structure to perform efficiently dynamic reconfiguration. The DUCK allows to separate the configuration path and the configuration registers which facilitates simultaneous configuration and computing steps. The reconfiguration process using the DUCK concept is presented in detail and synthesis results are given for different structures. Our solution is finally validated with the implementation of a WCDMA receiver on a multi-context embedded FPGA and demonstrates the interest and the efficiency of using dynamic reconfiguration.

1 Introduction

Systems on Chip (SOC) are based on three main kinds of architecture. First, Application-Specific Integrated Circuits (ASIC) allow to efficiently compute an algorithm due to dedicated hardware but are unfortunately inflexible. Secondly, processors are the most flexible architectures, but compute in an inefficient way. Finally, static reconfigurable architectures such as Field Programmable Gate

Area (FPGA) are considered a good compromise between processors and ASIC. Meanwhile, mixed architectures have been developed in order to improve the efficiency and the performance of processors by the use of static reconfigurable co-processors. These static reconfigurable co-processors embedded into a SoC, namely embedded-FPGA (e-FPGA), have allowed processors to follow application developments. Dynamic reconfiguration allows partial configurations at run-time, and thus improves performances. Multi-context FPGAs take advantage of dynamic reconfiguration in their architecture. This is achieved by the local storage of any possible context. When a new configuration is required, the system switches between one or the other context. The major drawback of this solution is the silicon area and power inefficiency caused by local memories needed to store all the contexts. Furthermore, to our knowledge, no e-FPGA with efficient dynamic reconfiguration features has been developed until now. Our contribution to multi-context FPGA is the definition of an optimized structure that supports dynamic, partial and run-time reconfiguration. This is performed by only two configuration memories, one current configuration memory and one parallel configuration memory. The parallel configuration memory is used for loading or saving context for preemption to or from the configuration memory in on one clock cycle. New contexts are stored in this parallel configuration memory thanks to a splittable scan-chain. Compared to multi-context FPGA, configurations exploit efficiently the available silicon resources.

The paper is structured as follows. Section 2 describes related works on optimization of multi-context FPGA. Section 3 presents our contribution on dynamically reconfigurable e-FPGA. In Section 4, we present the experimental method and discuss results on a WCDMA receiver implementation on an e-FPGA. Finally, Section 5 sums up this paper.

2 Related Works

For a decade, many dynamically reconfigurable architectures have been developed, mainly reconfigurable processors. The only fine-grain architectures which implement dynamically reconfigurable computing are multi-context FPGA. Industrial FPGAs (e.g. Xilinx Virtex family) allow dynamic reconfiguration, but the reconfigured resources have to be stopped before a new configuration can be propagated. Different approaches have been proposed in the literature to re-

duce the excessive silicon area used by multi-context FPGAs. First, some works focus on the reduction of the configuration words. In [1], the method consists in the limitation of the connection map inside a switch box. In [2], the authors reduce the context memory by using redundancy and regularity in the configuration data. The first method has the disadvantage to reduce routability. The second is efficient only in good conditions of redundancy and regularity, which is not the case for all applications. The second approach [3] is a technological solution which consists in the use of DRAM memories instead of SRAM usually implemented for storing configuration contexts. This allows to save between 10% and 60% transistors, but causes a new problem concerning mixed process of DRAM and logic.

3 Efficient dynamic reconfiguration on e-FPGA

3.1 Dynamic Unifier and reConfiguration block (DUCK)

As seen Section 2, multi-context reconfiguration has provided solutions for fast reconfiguration on e-FPGA but generates redundant resources (local context memories) which contribute to a power inefficient design even if some solutions have been developed. However, the solution that we propose in this paper needs only one context memory for each resource. But, using only one context memory means that it is necessary to develop other architectural concepts in order to maintain the time constraints and the flexibility required by today's applications. The first concept of our contribution consists in the isolation of the configuration paths and the configuration resources which allows to prepare new contexts during the computation. The Dynamic Unifier and reConfiguration block (DUCK) is in charge of the configuration path and has to swap the required contexts to the configuration registers when needed. The second concept consists in the possibility to split the configuration path while maintaining a unique computing path in order to propagate the configuration through several configuration paths at the same time. Fig.1 shows an example of the implementation of the DUCK concept in an e-FPGA. This basic example implements a 2D-array of interconnection resources (depicted as an hexagon) associated to computing resources (depicted in the same color as the interconnection resources). For each resource (either interconnection or computing) one DUCK

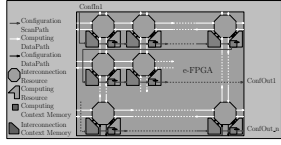


Figure 1: Example of an e-FPGA based on a 2D-array of interconnection and computing resources

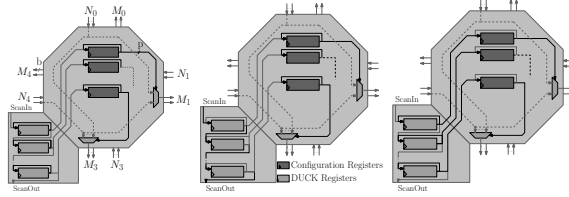


Figure 2: Reconfiguration process inside the DUCK structure

is associated and composes the configuration path (black arrow in bold print). The inputs of the two configurations paths represented by the name $ConfIn(i)$ and the output by the name $ConfOut(i)$. When the system is ready to reconfigure, each DUCK swaps the configuration context from its internal registers to the control registers. Configurations are swapped through the data path depicted in grey arrow on Fig.1. Once the configuration is swapped, it is possible to extract the context through the configuration path.

3.2 Dynamically reconfigurable e-FPGA

3.2.1 DUCK for interconnection resources

In our e-FPGA architecture, as for every FPGA, the communication resources (DyRIBox for Dynamically Reconfigurable Interconnection Box) switch signals from input ports to output ports. Each DyRIBox has n_i inputs and m_i outputs on b bits at each i of its four sides (North, South, West, East). The total number of input and output ports is therefore $N = \sum_{i=0}^3 n_i$ and $M = \sum_{i=0}^3 m_i$ respectively. Depending on the value of the configuration register, each input can be connected to one or several outputs. To reduce the complexity and the size of the configuration stream of the DyRIBox, the number of inputs that can be switched to an output is set to P , with $P \leq N$. Therefore, the DyRIBox contains M configuration registers of $\lceil p = \log_2 P \rceil$ bits.

In case of classical dynamic reconfiguration, the reconfiguration time is too

long for the given time constraints. To reduce this time, the reconfiguration process of the DyRIBox and of the computing resources is based on DUCK context registers (Fig.2). Each configuration register is connected to one context register contained in the DUCK resource and data could be swapped when needed. In order to manage the reconfiguration process, all DUCK registers are interconnected through a scanpath bus. Scanpath registers are used in design-for-test (DFT) techniques instead of classical registers in order to extract the register value at any time. The scanpath bus creates a unique big shift register with all the scanpath registers of the architecture. Thus, the extracted data flow is compared with the test vectors during testing to detect errors in the computing path. This method has been cited in [4] for applying preemption in reconfigurable architectures but has not yet been implemented. This was due to the fact that the extraction time was too long for the given time constraint required by today's applications.

The use of the configuration path in a scanpath manner associated with the DUCK concept allows the system to be reconfigured in one clock cycle. The use of the DUCK registers allows the system to prepare the next configuration while it is computing. The propagation of a new context is done by three different steps. The first one (Fig.2(a)) is the normal step: the configuration registers are already loaded with the current context. The DUCK registers are waiting for the next step. Either the new configuration is already propagated, or either they are waiting to be configured. The second step (Fig.2(b)) shows how a new configuration is spread to the DUCK registers. As explained before, the DUCK are connected in a scanpath manner which allows to propagate the next context. In case of preemption, the process is still the same for extraction of the previous context. Finally, the last step (Fig.2(c)) shows how a DUCK register swaps its data with the configuration register. Every configuration register is directly connected to a DUCK register. It is noteworthy that in case of a new configuration identical to the current one, the configuration swap does not disrupt the interconnection and computing resource behavior. Therefore, reconfiguration is possible even if a computing datapath crosses a reconfiguration area which it does not belong to.

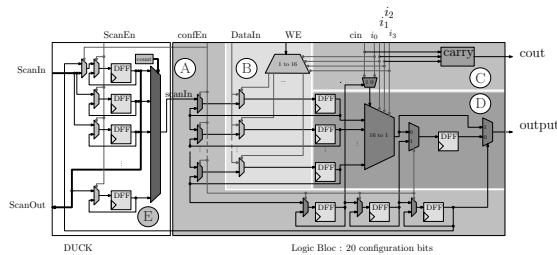


Figure 3: Simple logic cell architecture developed for fast reconfiguration

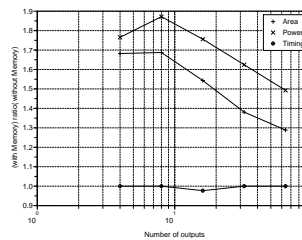


Figure 4: Influence of DUCK parameters on area, power and time

3.2.2 DUCK Applied to Computing Resources

Today's SOC use very different kinds of computing resources, so that, for every new dynamically reconfigurable architecture or computing resources, it becomes more difficult to extract an homogeneous reconfiguration protocol. The DUCK aims to solve this issue. For example, considering a classical logic cell (gray area on Fig.3) as the one we used for our e-FPGA, several resources are part of it. The reconfiguration path (area A) allows to set or reset the output register, to select the sequential or combinatorial output, and to select the carry input. The memory area (B) allows to use the logic cell as a RAM memory. The carry resources are needed for arithmetic operations (area C). The LUT resources are needed for the implementation of logical functions (area D).

The configuration path goes through all configuration registers and LUT registers. In this example, one logic cell needs 20 clock cycles to be reconfigured. Thus, for an e-FPGA composed of a $n \cdot m$ array of logic cells, $n \cdot m \cdot 20$ clock cycles are needed to reconfigure the whole FPGA. This time is not acceptable for fast reconfiguration. Our solution, the DUCK (area E of Fig.3) allows to shift the configuration context locally in the same way as for the DyRIBox and to swap the reconfiguration when needed. Therefore, the whole embedded FPGA can be reconfigured in 20 clock cycles. In the DUCK, a counter selects each configuration register one after the other and shifts it to the logic cell configuration path.

Technique	Area in mm^2	Critical Path in ns	Power in mW
4S project	0.0506	930	17.32
DyRIBox	0.0526	692	7.22

Table 1: Synthesis results compared with the 4S project solution

	FIR	Searcher	Rake Receiver	
			a Finger	All
Logic cells	3475	4953	561	4488
Total	12916			

Table 2: Necessary logic-cells for WCDMA decoder implementation on a dynamically reconfigurable architecture

3.3 Results and Exploration

This section presents exploration results on the DUCK parameters. First, synthesis results are given to estimate the variation of the silicon area the size of outputs and inputs and the number of possible connections to one output are changed. The critical path and power consumption are also analyzed. All results are expressed as a function of the computing data bitwidth. Results are obtained with the synthesis tool Design Compiler from Synopsys and for a $130nm$ CMOS technology.

The influence of DUCK parameters on design area, power and critical path is given in Fig.4. The results have been obtained by changing the number of outputs on the DyRIBox. First, the DUCK has clearly no influence on the critical path results because of the physical separation of the configuration path and the configuration registers in the DyRIBox. Secondly, the more connection possibility the DyRIBox has, the less importance the DUCK in the design area has. This is explained by the fact that the silicon area used for the interconnection wires between inputs and outputs grows faster than the silicon area used by the configuration/DUCK memories. Due to custom libraries used for 8-bit words, the power consumption is better controlled from this bitwidth than for 4-bit data.

The interconnection network presented in [5] consists in a set of reconfigurable circuit-switched routers interconnected by links. One router is composed of five 16-bit bi-directional ports connected through a 16×20 fully connected crossbar. We have generated and synthesized a DyRIBox associated to a DUCK with the same functionality. Area, frequency and power after synthesis are given for the two solutions in Tab.1. These results show that the simplicity of our solution allows to keep as many flexibility as in their solution, whereas our struc-

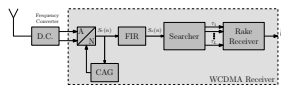


Figure 5: WCDMA receiver synoptic

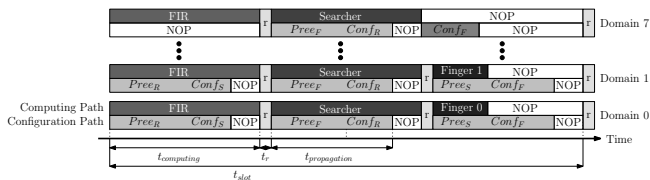


Figure 6: Gantt diagram of the computing and reconfiguration process

ture has only 4% area overhead and a gain of 25% on the critical path and 69% in power.

In conclusion, fast dynamic reconfiguration is made possible by the use of the DUCK concept: the separation of configuration path and the configuration registers. A small overhead of silicon area for each logic cell and interconnect box is involved by our method, but on the other hand, the reconfiguration itself allows to save resources compared to multi-context FPGAs. Furthermore, to maintain the timing constraint, it is necessary to propagate each new context as fast as possible, so that the new tasks can swap in the most efficient way. That is realized by the introduction of the split configuration path. Indeed, when several configuration paths are created, it is possible to propagate new contexts in parallel with each configuration path. This method allows to reduce the propagation time with regard to the number of configuration path used. The following case study gives more precise results about saved resources on a telecommunication application.

4 Case-study

In this section, we present the implementation of a W-CDMA (Wideband Code Division Multiple Access) receiver on our embedded FPGA (Fig.7). W-CDMA is a high-speed transmission protocol used in third generation mobile communication systems such as UMTS (Universal Mobile Telecommunications System), and is considered as one of the most critical application of third-generation telecommunication systems. It is based on the CDMA access technique where all data sent within a channel and for a user have to be coded with a specific code to be distinguished from the data transmitted in other channels [6]. The num-

ber of codes is limited and depends on the total capacitance of the cell, which is the area covered by a single base station. To be compliant with the UMTS radio interface specification (UTRA – Universal Terrestrial Radio Access), each channel must achieve a data rate of at least 128kbps. The theoretical total number of concurrent channels is 128 channels. As in practice only about 60% of the channels are used for user data, the WCDMA base-station can support 76 users per carrier.

The W-CDMA application executed on our reconfigurable architecture consists in the alternate execution of three main tasks (Fig.5): *FIR (Finite Impulse Response) filter*, *Searcher*, and *Rake Receiver*. Within a WCDMA receiver, real and imaginary parts of the signal received on the antenna after demodulation and digital-to-analog conversion, $S_r(n)$, are filtered by a FIR (Finite Impulse Response) *shaping filters*. Since the transmitted signal reflects in obstacles like buildings or trees, the receiver gets several replica of the same signal with different delays and phases. By combining the different paths, the decision quality is drastically improved. Consequently, the *Rake Receiver* combines the different paths extracted by the *Searcher* block in order to improve the quality of the symbol decision. Each path is computed by one *finger* which correlates the received signal by a spreading code aligned with the delay of the multipath signal. In our case, a maximum number of fingers are considered. This task is realized at the chip rate of 3.84 MHz. The decision is finally done on the combination of all these despreaded paths.

4.1 Timing Constraints

WCDMA is the highest speed transmission protocol used in the UMTS system. The bandwidth of the transmitted signal is equal to 5 MHz. The frequency of the code corresponding to the chip rate (F_{chip}) is fixed to 3.84 MHz. One slot is composed of 256 chip data. Registers are used to pipeline data while *FIR*, *Searcher* or *Rake Receiver* are computing on one slot. For better synchronization results, the received chips is 4-time over-sampled. The computing time available for the three functions (*FIR*, *Searcher*, and *Rake Receiver*) is therefore $t_{slot} = 66.6\mu s$ between the computation of two consecutive slots. The *FIR* and *Searcher* computes on 1024 samples while one *Finger* of the *Rake Receiver* computes on 256 samples. One sample is computed at each clock cycle.

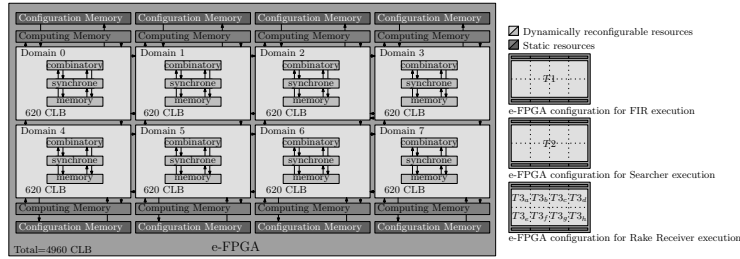


Figure 7: Resource allocation of the implemented embedded FPGA

4.1.1 Computing complexity

Table 2 presents synthesis results obtained with the MADEO framework [7]. The most complex function, the searcher, requires 4953 logic cells to be configured in the e-FPGA. It is therefore possible to implement the whole WCDMA decoder into 4953 logic cells using dynamic reconfiguration. To illustrate dynamic reconfiguration, the three functions are executed sequentially in a slot time of $66.6\mu s$ i.e. $22.2\mu s$ for each function. Therefore, each function is executed during $22.2\mu s$ while the next context is propagated.

As said previously, each function is completed in 1024 clock cycles, and the clock frequency is therefore greater than 46.55 MHz. The logic cell critical path has a value of $0.6ns$ in a $130nm$ CMOS technology. Considering that the functions have a critical path of 13 logic cells, the computing frequency can be up to 128.2 MHz. For a better power consumption, the frequency can be reduced to a lower value maintaining the time constraint. For this implementation, the computing frequency is set to 50 MHz ($t_{computing} = 20.48\mu s$).

4.1.2 Reconfiguration complexity

To perform dynamic reconfiguration, 4953 logic cells need to be reconfigured in less than $22.2\mu s$. One logic cell has 20 reconfiguration bits and a DyRIBox 10 bits. A 6-bit width configuration path is used for its good trade-off between performance and silicon area. Therefore, $4953 \times 30/6 = 24765$ 6-bit words are needed for each context. Thanks to our system architecture, the global configuration is split into 8 reconfiguration domains managed in parallel (Fig.7).

4.2 Implementation Results

Figure 7 shows the implemented architecture with 8 domains of 620 logic cells. Static memory is used to allow data exchange between each functions. The *FIR* and *Searcher* functions require all the 8 domains to be configured. Assuming that a *Finger* implementation requires 561 logic cells, one domain is used for each *finger*. The 59 remaining logic cells are used to realize the decision on symbol. Figure 6 shows that the process of propagation, computing and reconfiguration is fast enough to maintain the time constraint thanks to the DUCK resources in the DyRIBox and the logic cell. The synthesis results the silicon overhead of the added local configuration memories. The overhead silicon area of the DUCK resource is $998\mu m^2$ for a DyRIBox and $1468\mu m^2$ for a logic cell. Considering that 4960 of the two resources are implemented, the overall area overhead can be estimated at $12.23mm^2$. It is important to notice that 12926 logic cells should have been used for a static implementation. Our implementation using dynamic reconfiguration consumes 7966 logic cells less than the static implementation. Considering that the silicon area needed for a logic cell is $2160\mu m^2$ and $6850\mu m^2$ for a DyRIBox, we can estimate the saved area to $59mm^2$.

Finally, Table 3 compares the same WCDMA decoder implemented in a Xilinx Virtex FPGA. It can be easily concluded that a dynamic reconfiguration is not possible on the Virtex since the reconfiguration of the entire FPGA takes more than $2ms$ [8] with a configuration frequency of $60MHz$ and with the SelectMAP interface which enable 8-bit word configuration.

5 Conclusions

In this paper, a new fast dynamically reconfigurable concept for embedded FPGA is proposed. This method allows to use an FPGA technology and to

System	Logic Cell	Configuration Size (8-bit word)	Reconfiguration Time
e-FPGA	4960	36k	$22.2\mu s$
XCV200	5292	164k	2.53ms

Table 3: Comparison between results on an embedded FPGA solution and on a Virtex commercial FPGA

gain in flexibility and silicon area while maintaining timing constraint. The reconfiguration time is reduced compared to traditional FPGA. The proposed concept is based on a fast reconfigurable interconnect and on the possibility to split the reconfiguration areas into several parts. The fast reconfigurable interconnect developed in this paper allows to load the future context while the system computes and to limit the silicon area overhead. The possibility to split the reconfiguration area into several parts allows to propagate more configuration words in parallel. In the near future, we will explore to split the configuration path at design time in order to automatically get the best trade-off between speed performance and silicon area.

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