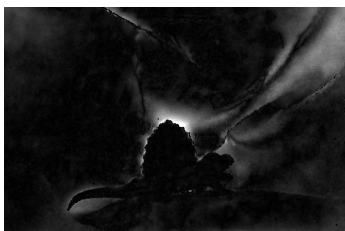


Motion Field \hat{v}



End Point Error: 0.19



Barron Angular Error: 3.30°



Likelihood robust weights \hat{z}_d



Prior robust weights \hat{z}_r (horizontal cliques)



(vertical cliques)