

To use Model checking for Control design

- Problem:
- Hybrid systems are **undecidable**
 - Decidable models of CS are currently **unusable**

MLQA mission statement:

“This spans [...] *resource usage* (e.g. ‘the control system rotates and adjusts the windmill such that at least 60 % of the potential wind energy is utilised’).”

- Highly **non-linear** system !
- Non-linear hybrid systems are undecidable
- State of the art: *Abstraction* to **discrete** system
- or to discrete-time or real-time system (e.g. **timed automata**)
- Problem: abstraction **too coarse** \implies unusable for most examples
- Badly need **finer abstractions**
- Good candidate: **Priced timed automata**
- Algorithms; tool support

Watch us in Aalborg...