

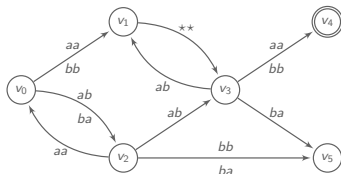
Games with arbitrarily many players

Nathalie Bertrand - Inria Rennes

joint work with Patricia Bouyer and Anirban Majumdar

CFV online seminar - June 5th 2020

2-player concurrent games



How to play?

- ▶ token is initially in vertex v_0
- ▶ Player 1 and Player 2 choose actions simultaneously
- ▶ next vertex is determined by the combination of actions

Player 1 has a **winning strategy** if she can win whatever Player 2 does

Motivations for parameterized concurrent games



a distinguished agent
trying to achieve a goal against
arbitrarily many adversaries

Eve vs Rest of the world

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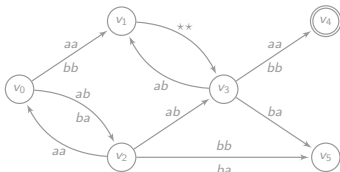


arbitrarily many agents
trying to achieve a goal
as a coalition

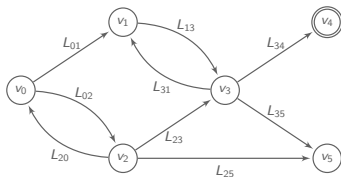
Strategy synthesis for coalition

Framework for parameterized concurrent games

From 2 players to arbitrarily many

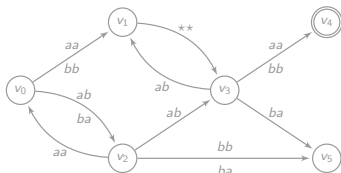


L_{ij} languages of finite words

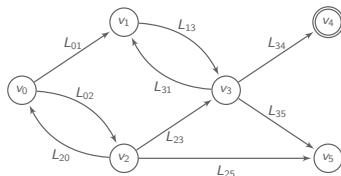


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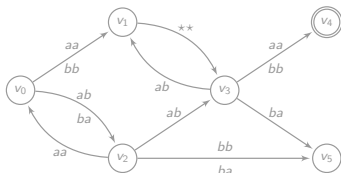


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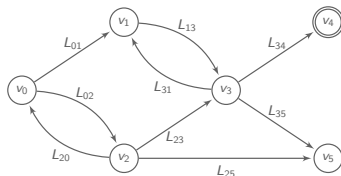
- ▶ number of players k is fixed initially, yet unknown to them
- ▶ players know their “position” (e.g. Player 3 is third in list)
- ▶ they observe the sequence of vertices
- ▶ each player chooses an action, forming altogether a finite word
 $\forall i$ Player i choosing a_i yields the word $\mathbf{w} = a_1 \cdots a_k$;
- ▶ to which language \mathbf{w} belongs determines the next vertex

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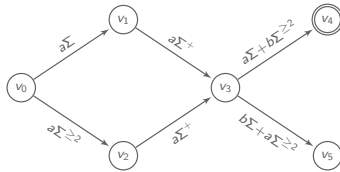
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Rk: choice of k and resolution of non-determinism is **adversarial**



A first parameterized reachability game

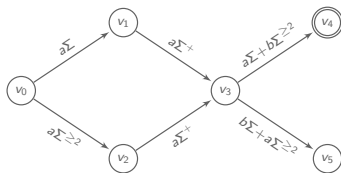
Eve vs Rest of the world





A first parameterized reachability game

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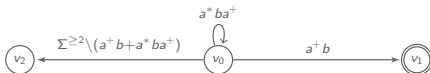


- ▶ game starts at v_0
- ▶ the number of players k is fixed but unknown to the players
- ▶ Player 1 plays a , other players each choose an action in Σ
- ▶ if $k = 2$, the token moves to v_1 , otherwise, it moves to v_2
- ▶ in v_3 , Player 1 can ensure to reach v_4 :
choose a (resp. b) if the play went to v_1 (resp. v_2)
- ▶ $v_0 \xrightarrow{aa} v_1 \xrightarrow{ab} v_3 \xrightarrow{aa} v_4 \in \text{Plays}_2$ $v_0 \xrightarrow{aab} v_2 \xrightarrow{abb} v_3 \xrightarrow{baa} v_4 \in \text{Plays}_3$

Player 1 can reach v_4 independently of the number of opponents

A second parameterized reachability game

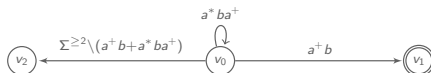
Strategy synthesis for coalition





A second parameterized reachability game

Strategy synthesis for coalition



- ▶ game starts at v_0
- ▶ the number of players k is fixed but unknown to the players
- ▶ as a coalition all players can ensure to reach v_1
at step i , Player i plays b and all others play a
- ▶ $\text{Play}_k = v_0 \xrightarrow{ba^{k-1}} v_0 \xrightarrow{aba^{k-2}} v_0 \cdots v_0 \xrightarrow{a^{k-1}b} v_1$

Players can collectively reach v_1 independently of their number

Formalization of our two problems of interest

Eve vs Rest of the world



Input: a parameterized arena, a winning objective **Win**

Output: whether Eve has a winning strategy to achieve **Win**

independently of the number of her opponents

$$\exists \sigma_E \forall k \forall \sigma_2 \cdots \sigma_k \text{ Plays}(\sigma_E, \sigma_2, \cdots, \sigma_k) \subseteq \mathbf{Win}?$$

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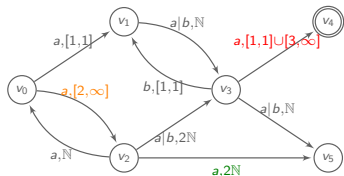
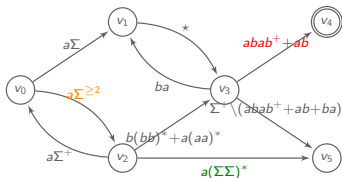
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Reduction to simpler games: counting is enough

Observation Eve's opponents act as a coalition

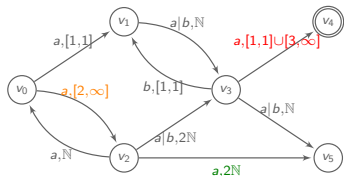
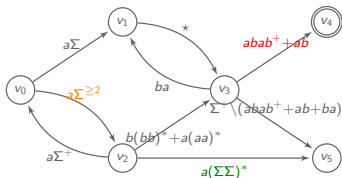
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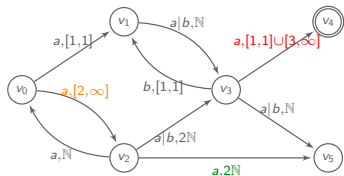
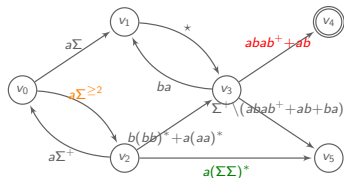
How to play?

- ▶ environment chooses number of players k , unknown to Eve
- ▶ at vertex v , Eve chooses action a
environment chooses edge $v \xrightarrow{a, S} v'$ with $k \in S$
- ▶ game proceeds from v'

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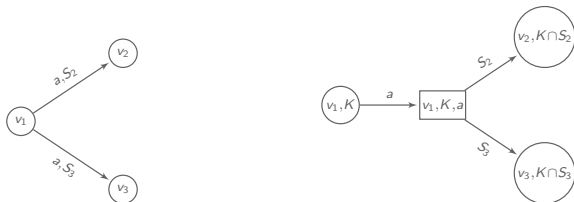
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Rk: for a regular language L , $\text{count}(L)$ is semi-linear

Knowledge game

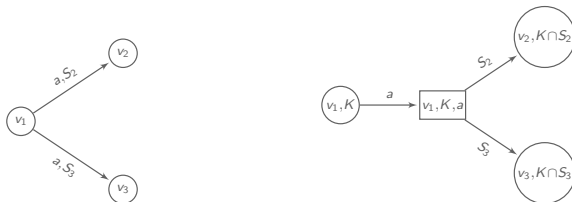
2-player turn-based game encoding Eve's knowledge on nb of opponents



- ▶ \circ chooses actions, \square chooses next vertex
- ▶ initial vertex (v_0, \mathbb{N}) owned by \circ
- ▶ knowledge of Eve is updated according to moves

Knowledge game

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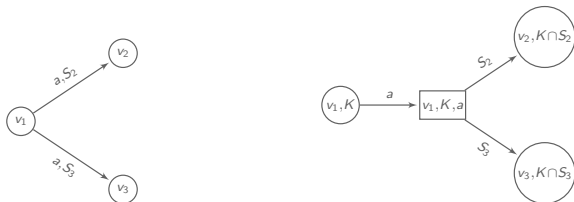


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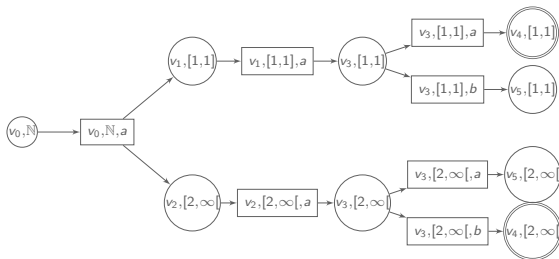
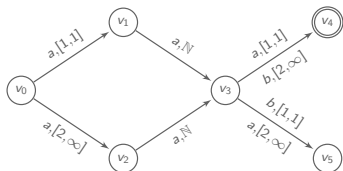


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Knowledge game can be solved in polynomial time in **its size**

Knowledge game on an example



Resolution of concurrent parameterized games

Decidability and complexity

The parameterized game problem for **reachability objectives** is decidable, with the following complexities

	Deterministic	Non-deterministic
Intervals	PTIME-complete	
Finite unions of intervals	NP-complete	PSPACE-complete
Semilinear sets	PSPACE-complete	

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Simple case of intervals

knowledge game is quadratic in the number of end-points

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Simple case of intervals

knowledge game is quadratic in the number of end-points

General case: semi-linear sets

knowledge game is at most exponential in the number of semilinear sets
but there is a polynomial space algorithm

PSPACE upper bound for semilinear constraints

Parameterized game problem for reachability objectives is in PSPACE

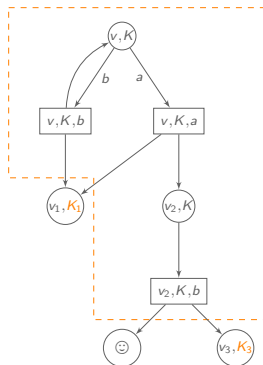
Proof idea

- ▶ decompose the knowledge game into subgames
with objective to reduce the knowledge while remaining winning
- ▶ DFS algorithm tagging states (v, K) with \checkmark/\times up to (v_0, \mathbb{N})

Close-up on subgames

for every \circ vertex (v, K)
restriction of the knowledge game

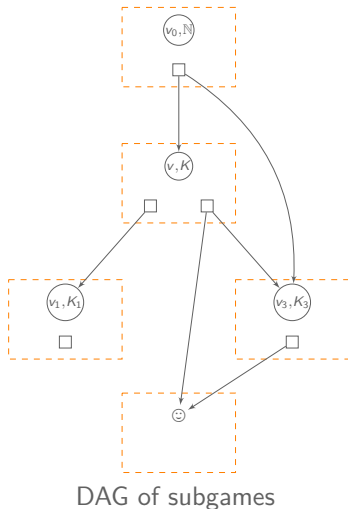
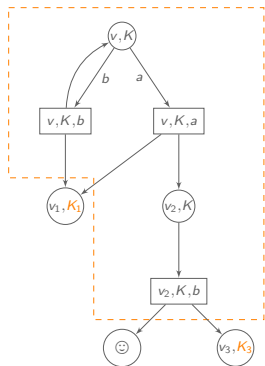
- ▶ starting at (v, K)
- ▶ stopping at any (v', K') with $K' \subsetneq K$
or at the target ☺



Close-up on subgames

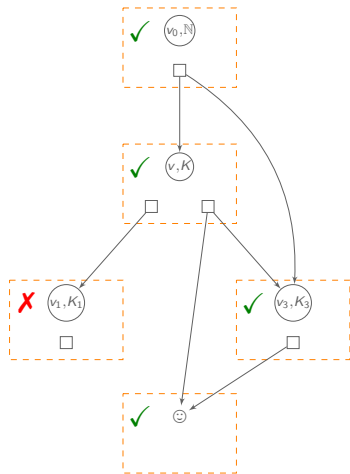
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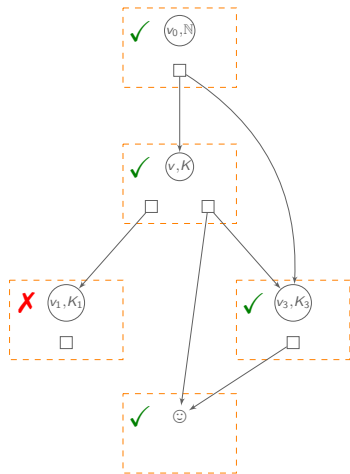


Close-up on tagging algorithm

- ▶ tag ☺ with ✓ other leaves with ✗
- ▶ tag (v, K) with ✓ if in the subgame starting at (v, K)
 - has a strategy to reach ✓



Close-up on tagging algorithm



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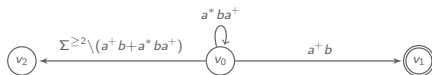
How to do this in PSPACE?

- ▶ in a DFS, store only subgames and tags that are relevant
- ▶ any subgame for (v, K) is of polynomial size and has polynomially many exits (v', K')
- ▶ the height of the DAG is polynomial
- ▶ once a tag is computed, one can forget the whole sub-DAG

Strategy synthesis for coalition

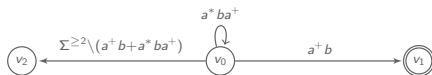


Strategy synthesis for coalition of arbitrarily many players



$\exists \sigma_1 \sigma_2 \dots \forall \mathbf{k} \text{ Plays}(\sigma_1, \sigma_2, \dots, \sigma_{\mathbf{k}}) \subseteq \mathbf{Win}?$

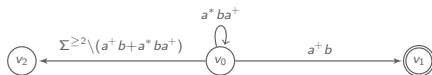
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At step i , Player i plays b and all others play a
is a winning coalition strategy to reach v_1

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Collective strategies map histories to ω -words

$$\vec{\sigma}(v_0^n) = a^{n-1} b a^\omega$$

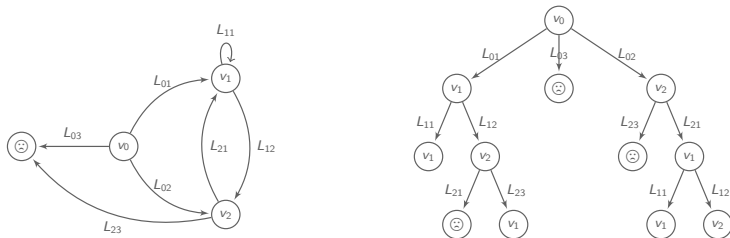
How to play?

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- ▶ at vertex v , players collectively choose an ω -word \mathbf{w}
 environment chooses edge $v \xrightarrow{L} v'$ with $\mathbf{w}_{\leq \mathbf{k}} \in L$
- ▶ players may learn some info about their number
- ▶ game proceeds from v'

Synthesis of collective strategy for safety objectives

From game arena build **tree unfolding** and stop

- ▶ either if the same label already appears for an ancestor
- ▶ or when label is ☹

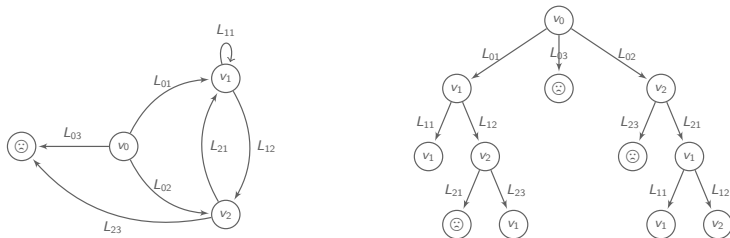


equivalently, coalition strategies map inner nodes of the tree to ω -words

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One can build a doubly exponential deterministic safety automaton over Σ^m ($m = \#$ inner nodes) that accepts winning strategies.

Existence of a winning coalition strategy is in EXPSPACE
(and PSPACE-hard)

Contributions

- ▶ Definition of concurrent games with arbitrary many players

- ▶ Eve vs Rest of the world 
 - ▶ reduction to knowledge game (2-player and turn-based)
 - ▶ reachability objectives are PSPACE-complete

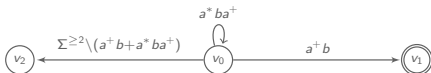
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On-going work

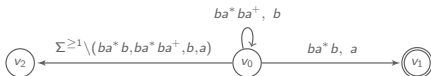


Strategy synthesis for coalition: reachability

A positive instance



A negative instance



- ▶ even for very basic arenas, the problem seems non trivial
- ▶ **challenge**: acceleration techniques seem needed both on knowledge and on ω -words