

# Parameterized verification of probabilistic selective broadcast networks

Gandalf 2015

Nathalie Bertrand

Inria Rennes Bretagne Atlantique, France

joint work with **Paulin Fournier** and **Arnaud Sangnier**

# Motivation

- Distributed algorithms (*mutual exclusion, leader election, ...*)
- Telecommunication protocols (*routing, ...*)
- Algorithms for *ad-hoc* networks
- Model for biological systems

# Motivation

- Distributed algorithms (*mutual exclusion, leader election, ...*)
- Telecommunication protocols (*routing, ...*)
- Algorithms for *ad-hoc* networks
- Model for biological systems

**All participants have the same behavior**

They form a **crowd**

[Esparza, STACS'14]

# Crowd networks

- Every process follows a same given protocol
- Processes can communicate, by either
  - Message passing
  - Shared variables
  - *Rendez-vous* communications
  - Broadcast communications
  - **Multi-diffusion (selective broadcasts)**

# Crowd networks

- Every process follows a same given protocol
- Processes can communicate, by either
  - Message passing
  - Shared variables
  - *Rendez-vous* communications
  - Broadcast communications
  - **Multi-diffusion (selective broadcasts)**

## Parameterized verification of crowd networks

**Does the network conform to a given specification independently of the number of participants?**

# In this talk

## Decidability and complexity of parameterized reachability problems in probabilistic networks

### Features:

- Probabilistic protocols
- Multi-diffusion communications
- Simple reachability questions

# In this talk

## Decidability and complexity of parameterized reachability problems in probabilistic networks

### Features:

- Probabilistic protocols
- Multi-diffusion communications
- Simple reachability questions

**Challenge:**  
parameterized system + non-determinism + probabilities

# Outline

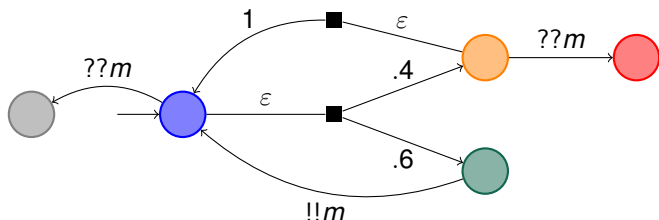
- 1 Probabilistic reconfigurable broadcast networks
- 2 Parity reconfigurable broadcast networks
- 3 Solving probabilistic networks via parity networks



# Outline

- 1 Probabilistic reconfigurable broadcast networks**
- 2 Parity reconfigurable broadcast networks
- 3 Solving probabilistic networks via parity networks

# A model for probabilistic protocols



## Probabilistic protocol

Finite state system whose transitions are labelled with:

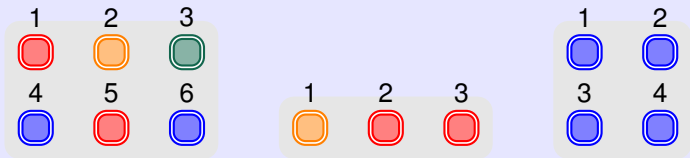
- 1 **probabilistic** internal actions -  $\varepsilon$
- 2 broadcast of messages -  $!!m$
- 3 reception of messages -  $??m$

for  $m$  in a finite alphabet  $\Sigma$ .

**A probabilistic protocol defines a probabilistic network**

# Configurations

Configurations: vectors of arbitrary size



- **Initial configurations:** **all** nodes are in the initial state

## Remarks:

- Size of configurations is not bounded

⇒ **Networks are infinite state systems**

# Probabilistic Networks: semantics

**Markov decision process** over set of configurations.

- $C$ : (infinite) set of configurations
- $\Rightarrow$ :  $C \times C \cup C \times \text{Dist}(C)$ : Transition relation
- $C_0$ : (infinite) set of initial configurations

**The number of nodes does not change along an execution**

# Probabilistic Networks: semantics

**Markov decision process** over set of configurations.

- $C$ : (infinite) set of configurations
- $\Rightarrow$ :  $C \times C \cup C \times \text{Dist}(C)$ : Transition relation
- $C_0$ : (infinite) set of initial configurations

**The number of nodes does not change along an execution**

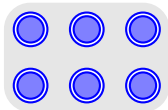
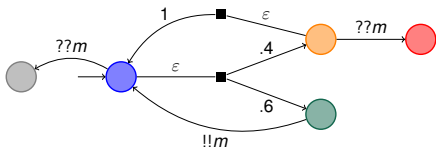
## Transition relation

Decomposed in three steps

- 1 Choice of a process
- 2 Choice of a reception set (= set of neighbours)
- 3 Execution of an action
  - **local action** - the process performs an internal action  $\varepsilon$
  - **communication** - the process sends a message ( $!!m$ ), and its neighbours receive it ( $??m$ ) if they can

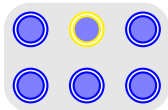
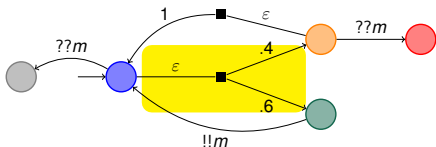
# Schedulers to resolve non-determinism

Scheduler  $\pi$  resolves the non-determinism by choosing the active process, its action and its neighbours



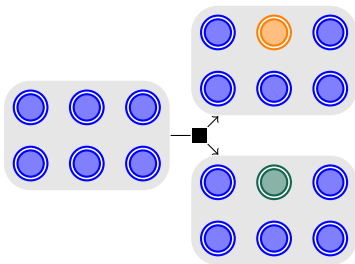
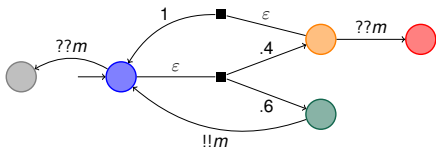
# Schedulers to resolve non-determinism

Scheduler  $\pi$  resolves the non-determinism by choosing the active process, its action and its neighbours



# Schedulers to resolve non-determinism

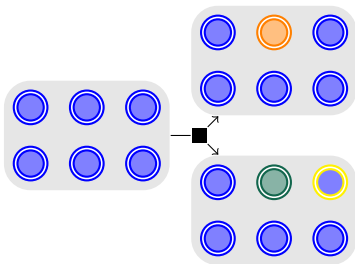
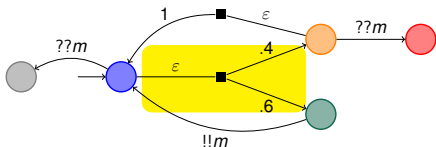
Scheduler  $\pi$  resolves the non-determinism by choosing the active process, its action and its neighbours





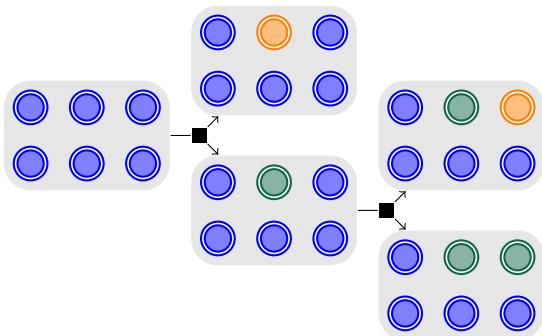
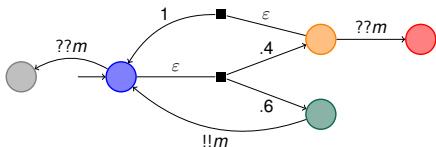
# Schedulers to resolve non-determinism

Scheduler  $\pi$  resolves the non-determinism by choosing the active process, its action and its neighbours



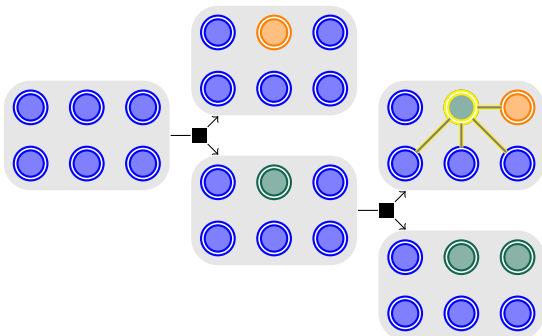
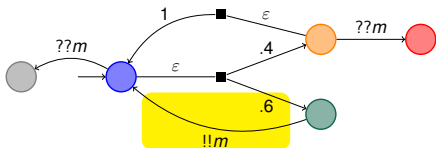
# Schedulers to resolve non-determinism

Scheduler  $\pi$  resolves the non-determinism by choosing the active process, its action and its neighbours



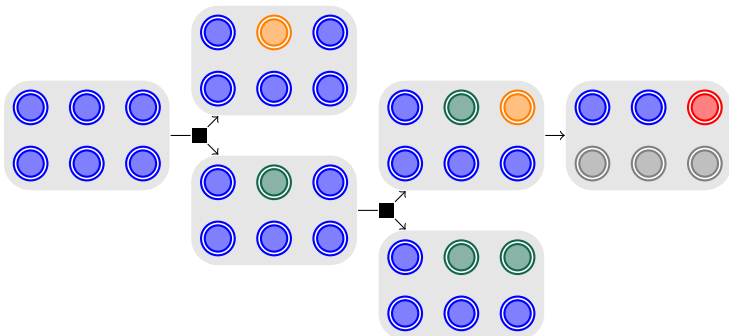
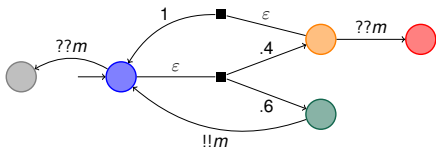
# Schedulers to resolve non-determinism

Scheduler  $\pi$  resolves the non-determinism by choosing the active process, its action and its neighbours



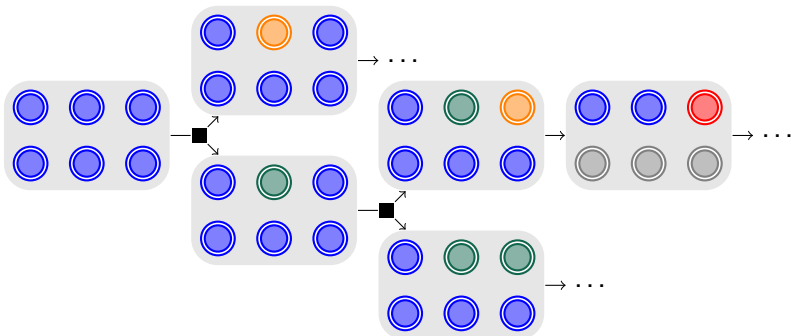
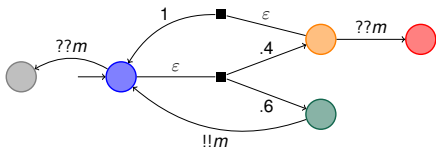
# Schedulers to resolve non-determinism

Scheduler  $\pi$  resolves the non-determinism by choosing the active process, its action and its neighbours



# Schedulers to resolve non-determinism

Scheduler  $\pi$  resolves the non-determinism by choosing the active process, its action and its neighbours



# Parameterized reachability problems

scheduler  $\pi$  on  $N$  nodes induce a finite Markov chain of measure  $\mathbb{P}_\pi^N$

# Parameterized reachability problems

scheduler  $\pi$  on  $N$  nodes induce a finite Markov chain of measure  $\mathbb{P}_\pi^N$

- Is an error state almost surely reachable, under some scheduler, and for some number of nodes?

$$\exists N, \exists \pi, \mathbb{P}_\pi^N(\diamond q_{\text{err}}) = 1$$

- Is an error state avoidable almost surely, under all adversarial schedulers, and for any number of nodes?

$$\forall N, \forall \pi, \mathbb{P}_\pi^N(\diamond q_{\text{err}}) = 0$$

# Parameterized reachability problems

scheduler  $\pi$  on  $N$  nodes induce a finite Markov chain of measure  $\mathbb{P}_\pi^N$

- Is an error state almost surely reachable, under some scheduler, and for some number of nodes?  $\text{REACH}_{\max}^1$

$$\exists N, \exists \pi, \mathbb{P}_\pi^N(\diamond q_{\text{err}}) = 1$$

- Is an error state avoidable almost surely, under all adversarial schedulers, and for any number of nodes?  $\neg \text{REACH}_{\max}^0$

$$\forall N, \forall \pi, \mathbb{P}_\pi^N(\diamond q_{\text{err}}) = 0$$

$\text{REACH}_{opt}^{\sim b}$

$opt \in \{\min, \max\}, \sim \in \{>, <, \leq, \geq, =\}, b \in \{0, 1\}$

**Input:** A process and a control state  $q_F \in Q$ ;

**Output:** Does there exists  $N$  such that  $opt \left\{ \mathbb{P}_\pi^N(\diamond q_F) \right\} \sim b$ ?



# Monotocity property and consequences

## Monotonicity

With more nodes in the network, the maximum reachability probability can only increase.

Idea: ignore additional nodes

# Monotocity property and consequences

## Monotonicity

With more nodes in the network, the maximum reachability probability can only increase.

Idea: ignore additional nodes

As a consequence, *e.g.*

$$\exists N, \exists \pi, \mathbb{P}_{\pi}^N(\diamond q_F) = 0 \iff \exists \pi, \mathbb{P}_{\pi}^1(\diamond q_F) = 0$$

$\text{REACH}_{\max}^=0$  is decidable in PTIME by considering a single node.

# Solving $\text{REACH}_{\max}^{>0}$

Does there exist a  $N$  and a scheduler  $\pi$  such that  $\mathbb{P}_{\pi}^N(\diamond q_F) > 0$ ?

- Equivalent to parameterized control state reachability
- **Decidable in PTIME** [Delzanno et al., FSTTCS'12]
- One can compute the set of reachable control states in PTIME
- Note: there exists an execution reaching a configuration with an arbitrary number of nodes in each reachable control state

Not as easy for  $\text{REACH}_{\max}^{=1}$ !

# Finite vs infinite MDPs

- Qualitative reachability is solvable in PTIME for finite MDPs by simple graph algorithms.
- Qualitative reachability in infinite-state MDPs: restricted to particular classes with *ad hoc* algorithms
  - non-deterministic and Probabilistic Lossy Channel Systems [Baier et al. 2007]
  - recursive Markov Decision Processes [Etesami et al. 2015]

# Finite vs infinite MDPs

- Qualitative reachability is solvable in PTIME for finite MDPs by simple graph algorithms.
- Qualitative reachability in infinite-state MDPs: restricted to particular classes with *ad hoc* algorithms
  - non-deterministic and Probabilistic Lossy Channel Systems [Baier et al. 2007]
  - recursive Markov Decision Processes [Etessami et al. 2015]
- Alternative technique in the finite case: transformation into  $\mu$ -calculus formula or parity game. [Chatterjee et al. 2007]

# Finite vs infinite MDPs

- Qualitative reachability is solvable in PTIME for finite MDPs by simple graph algorithms.
- Qualitative reachability in infinite-state MDPs: restricted to particular classes with *ad hoc* algorithms
  - non-deterministic and Probabilistic Lossy Channel Systems [Baier et al. 2007]
  - recursive Markov Decision Processes [Etessami et al. 2015]
- Alternative technique in the finite case: transformation into  $\mu$ -calculus formula or parity game. [Chatterjee et al. 2007]

## How to adapt this methodology to probabilistic networks?

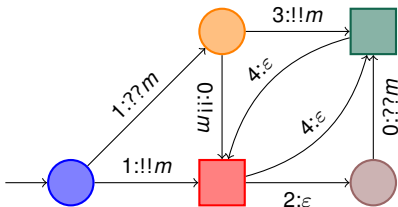
### Main issues:

- 1 Transform MDP into equivalent parity game **at the protocol level**
- 2 Solve parity networks






# Outline

- 1 Probabilistic reconfigurable broadcast networks
- 2 Parity reconfigurable broadcast networks**
- 3 Solving probabilistic networks via parity networks

# A model for parity protocol



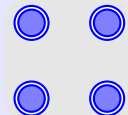
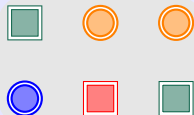
## Parity protocol

-    states of Player 1
-   states of Player 2
- Transitions are labelled with:
  - 1 internal actions from **Player 2's states** –  $\varepsilon$
  - 2 broadcast of messages –  $!!m$
  - 3 reception of messages –  $??m$
  - 4 parities in  $\mathbb{N}$



# Semantics

Configurations: vectors of arbitrary size



# Semantics

Configurations: vectors of arbitrary size



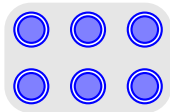
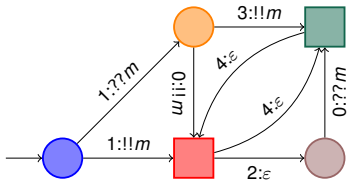
## Roles are asymmetric

- Player 1 chooses the active process, and its neighbours
- If the active process is in a Player  $i$ 's state, Player  $i$  chooses its action

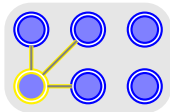
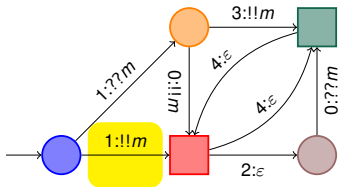
Strategy profile  $(\sigma, \tau)$  yields a play  $\rho$

In communication transitions, the parity is the one of the corresponding broadcast

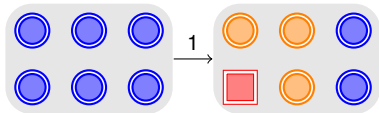
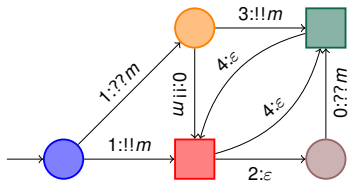
## An example of play



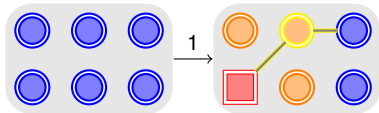
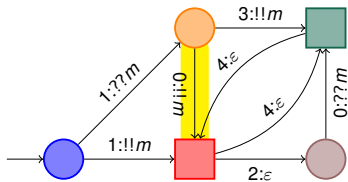
## An example of play



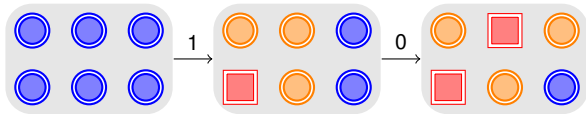
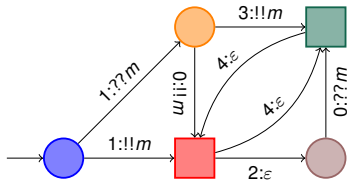
## An example of play



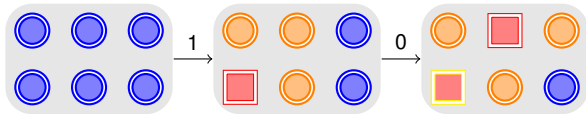
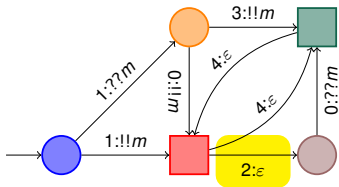
## An example of play



# An example of play

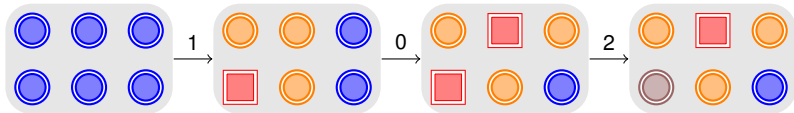
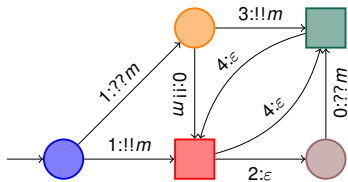


# An example of play

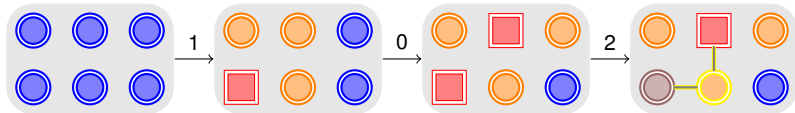
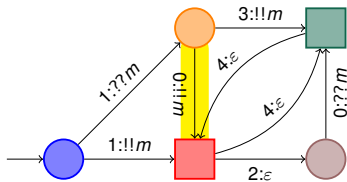




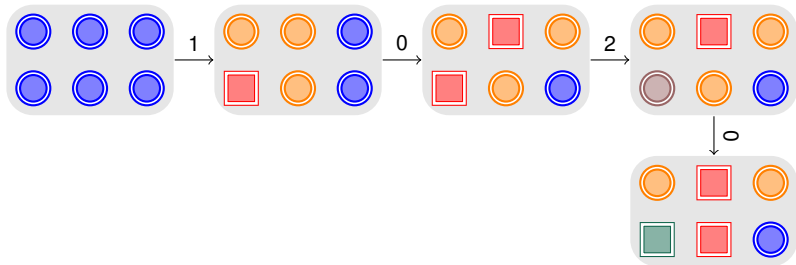
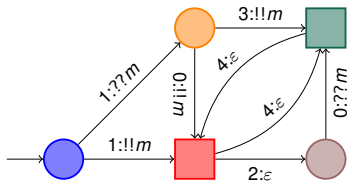
# An example of play



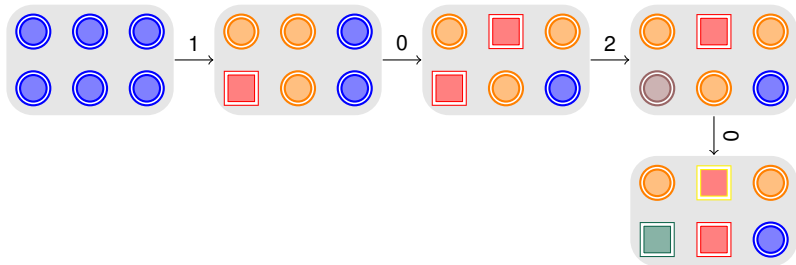
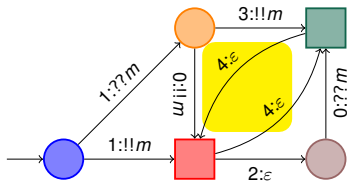
# An example of play



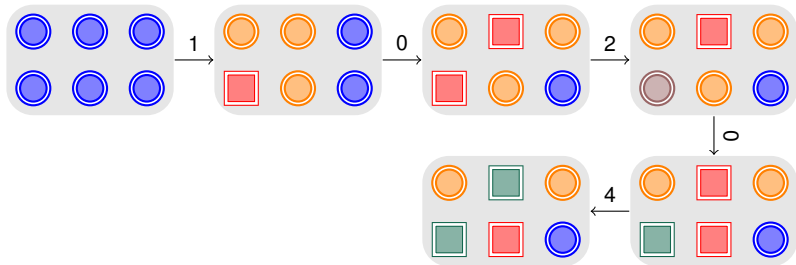
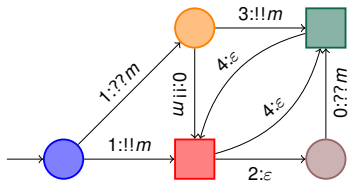
# An example of play



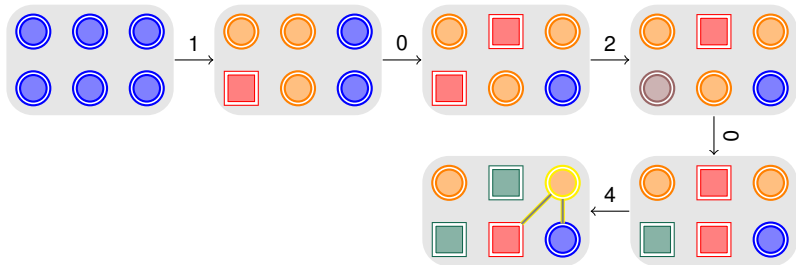
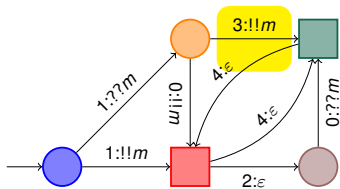
# An example of play



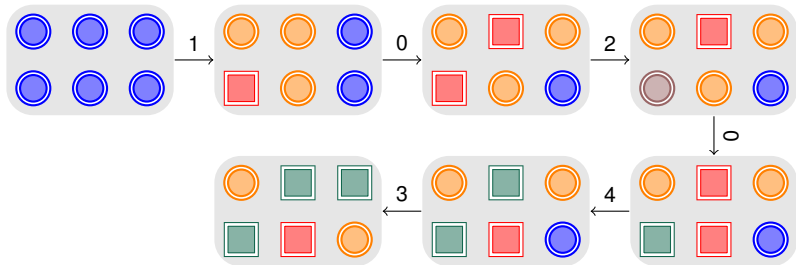
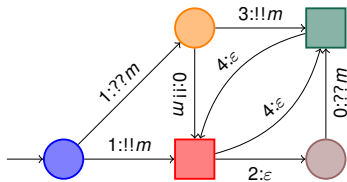
# An example of play



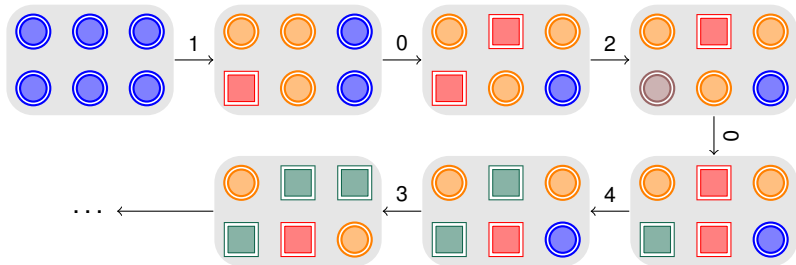
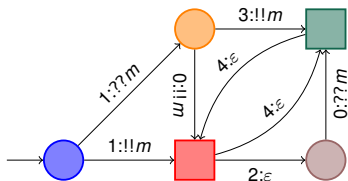
# An example of play



# An example of play



# An example of play





# Parameterized game problem

## Winning condition

*Win* consists of infinite plays such that the maximal color repeated infinitely often is even.

# Parameterized game problem

## Winning condition

*Win* consists of infinite plays such that the maximal color repeated infinitely often is even.

Does Player 1 has a winning strategy for the parity objective for some number of nodes?

## Game problem for parity networks

**Input:** A parity protocol  $P$

**Question:** Does there exists  $N$  and a strategy  $\sigma$  for Player 1 such that for all strategies  $\tau$  for Player 2  $\rho(\sigma, \tau, N) \in \textit{Win}$ .

# Solving games on parity networks

Two steps

- 1 state-based strategies for Player 2 are enough
- 2 decidability of the existence of an infinite cycle in reconfigurable broadcast networks (*i.e.* networks of 1-player games)

## State-based strategies


- only depend on the control state labeling the active node
- there are finitely many
- given a fixed state-based strategy for Player 2, one obtains a reconfigurable broadcast network

# Step 1: Restricting to state-based strategies

## Proposition

If there exists a number of nodes such that Player 1 has a winning strategy against any state-based strategy of Player 2, then there exists a number of nodes such that Player 1 has a winning strategy against any strategy of Player 2.

Proof by induction of the number of states of Player 2

- For the induction step, isolate a Player 2 state  with two possible internal actions  $\varepsilon_L$  and  $\varepsilon_R$
- By induction, if edge  $\varepsilon_R$  is deleted, Player 1 has a winning strategy  $\sigma_L$  for  $N_L$  nodes, and symmetrically
- A winning strategy is obtained combining  $\sigma_L$  and  $\sigma_R$  on  $N_L + N_R$  nodes

# Building a strategy using $\sigma_L$ and $\sigma_R$

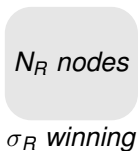
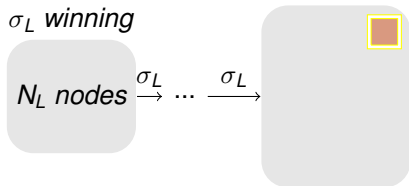
$\sigma_L$  winning

$N_L$  nodes

$N_R$  nodes

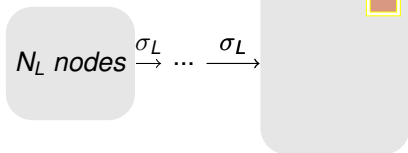
$\sigma_R$  winning

# Building a strategy using $\sigma_L$ and $\sigma_R$

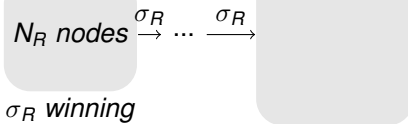


# Building a strategy using $\sigma_L$ and $\sigma_R$

$\sigma_L$  winning



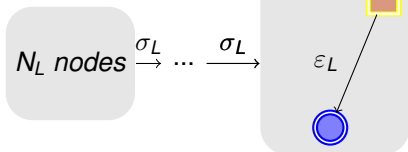
$N_R$  nodes



$\sigma_R$  winning

# Building a strategy using $\sigma_L$ and $\sigma_R$

$\sigma_L$  winning



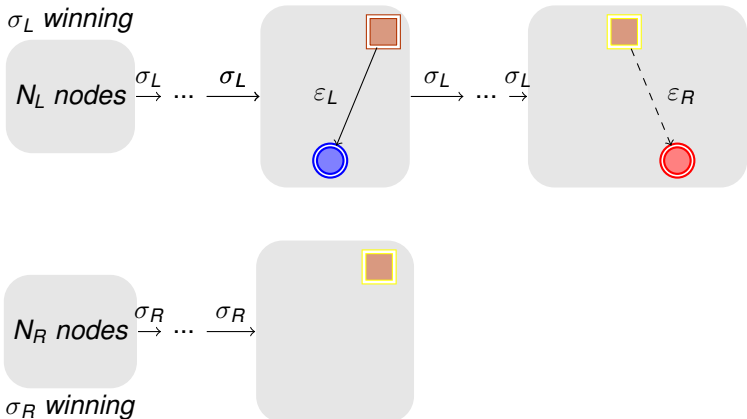
$N_R$  nodes



$\sigma_R$  winning

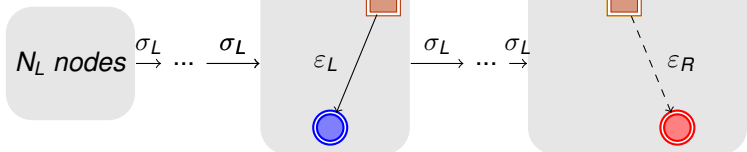


# Building a strategy using $\sigma_L$ and $\sigma_R$



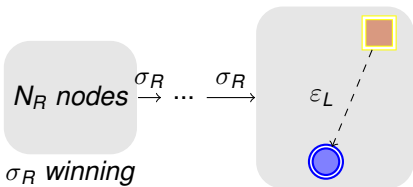
# Building a strategy using $\sigma_L$ and $\sigma_R$

$\sigma_L$  winning

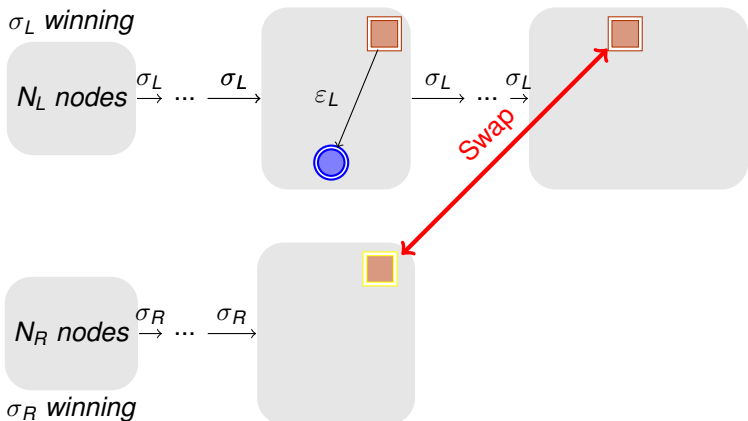


$N_R$  nodes

$\sigma_R$  winning

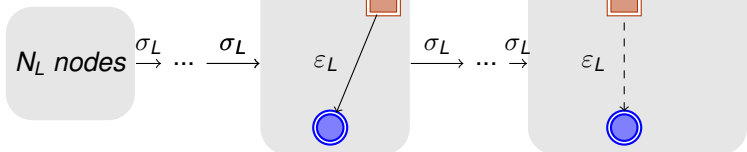


# Building a strategy using $\sigma_L$ and $\sigma_R$



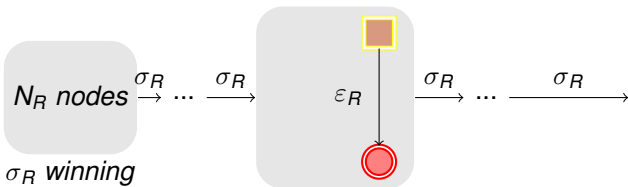
# Building a strategy using $\sigma_L$ and $\sigma_R$

$\sigma_L$  winning



$N_R$  nodes

$\sigma_R$  winning



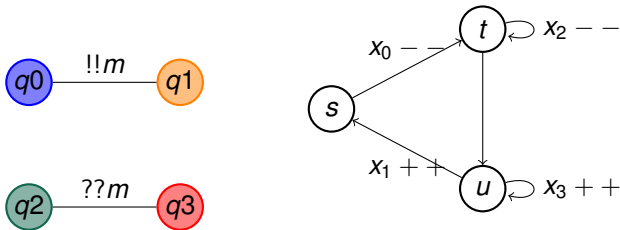
# Test animation

## Step 2: Detecting infinite paths

- For a fixed state-based strategy for Player 2, one obtains a reconfigurable broadcast network
- One can compute its set of reachable control states; there exists an execution reaching a configuration with an arbitrary number of nodes in each reachable state

## Step 2: Detecting infinite paths

- For a fixed state-based strategy for Player 2, one obtains a reconfigurable broadcast network
- One can compute its set of reachable control states; there exists an execution reaching a configuration with an arbitrary number of nodes in each reachable state
- An infinite path corresponds to a positive cycle in a vector addition system with states (VASS)



- Detecting positive cycles in VASS can be done in PTIME [Kosaraju & Sullivan 1988]

# Deciding the game problem for parity networks

## Theorem

The game problem for parity RBN is in  $\text{coNP}$ .

### Proof idea:

- Guess a state-based strategy  $\tau$  for Player 2
- Check whether it is winning for any number of nodes and against any strategies for Player 1
  - If the VASS has a positive cycle,  $\tau$  it is not winning
  - Can be decided in  $\text{PTIME}$
- If the state-based strategy  $\tau$  is winning, then return NO

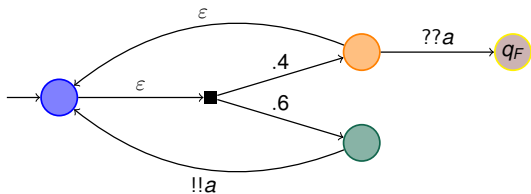


# Outline

- 1 Probabilistic reconfigurable broadcast networks
- 2 Parity reconfigurable broadcast networks
- 3 Solving probabilistic networks via parity networks**

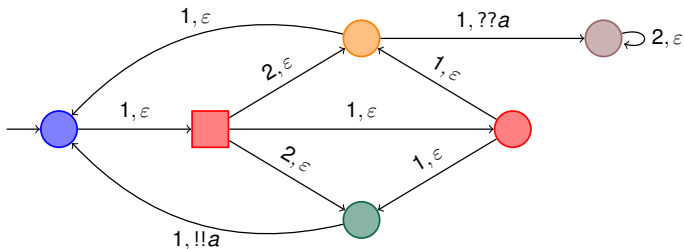
**Solving REACH<sub>max</sub><sup>=1</sup>** :  $\exists N, \exists \pi, \mathbb{P}_\pi^N(\diamond q_F) = 1$

# Solving $\text{REACH}_{\max}^1$ : $\exists N, \exists \pi, \mathbb{P}_{\pi}^N(\diamond q_F) = 1$



Idea of the reduction:

- Player 2 decides the outcome of probabilistic choices
- Fairness is ensured using parities



# Correctness of the reduction for $\text{REACH}_{\max}^1$

configurations in prob. network  $\equiv$  configurations in parity network  
schedulers  $\equiv$  Player 1 strategies

# Correctness of the reduction for $\text{REACH}_{\max}^1$

configurations in prob. network  $\equiv$  configurations in parity network  
schedulers  $\equiv$  Player 1 strategies

**Key:**  $\text{REACH}_{\max}^1$  iff from every reachable configuration there is a path to a target configuration

# Correctness of the reduction for $\text{REACH}_{\max}^1$

configurations in prob. network  $\equiv$  configurations in parity network  
schedulers  $\equiv$  Player 1 strategies

**Key:**  $\text{REACH}_{\max}^1$  iff from every reachable configuration there is a path to a target configuration

## Proof idea:

- If Player 1 has a winning strategy
  - case 1** Player 2 always decides the outcome of probabilistic choices; corresponds to paths in null measure set
  - case 2** Player 2 eventually always leave decision to Player 1; from each reachable configuration, there is a path to the target
- If Player 1 has no winning strategy  
For every  $\sigma$ , Player 2 eventually lets Player 1 decide the outcome of probabilistic choices;  
there exists a configuration from which target is not reachable

# Complexity of almost-sure reachability

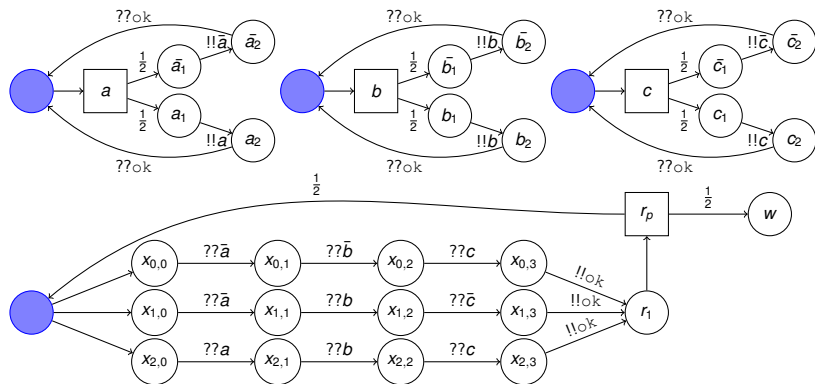
## Theorem

$\text{REACH}_{\max}^1$  is CONP-complete.

- membership in NP by reduction to games on parity networks
- NP-hardness is obtained by reducing UNSAT

# NP-hardness of almost-sure reachability

$$\varphi = (a \vee b \vee \bar{c}) \wedge (a \vee \bar{b} \vee c) \wedge (\bar{a} \vee \bar{b} \vee \bar{c})$$



If  $\varphi$  is UNSAT, for any assignment, choose a clause so that the probability to reach  $w$  is .5.



# Conclusion

## Summary

- **model:** probabilistic selective broadcast networks
- **properties:** parameterized qualitative reachability questions
- **resolution:** via parity networks, yet another new model
- **complexities:** PTIME or CONP-complete

# Conclusion

## Summary

- **model:** probabilistic selective broadcast networks
- **properties:** parameterized qualitative reachability questions
- **resolution:** via parity networks, yet another new model
- **complexities:** PTIME or CONP-complete

## Perspectives

- move to quantitative questions
- beyond reachability
- consider other communication means
- logical characterization of parameterized parity games
- schedulers taking into account processes local view