

Probabilistic and Topological Semantics for Timed Automata

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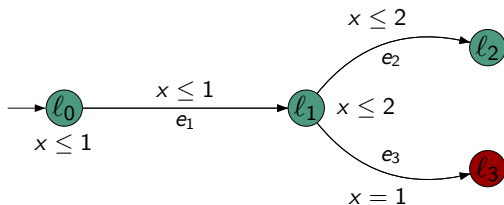
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Motivation

- ▶ Timed automata: idealized mathematical model
 - ▶ infinite precision
 - ▶ instantaneous events

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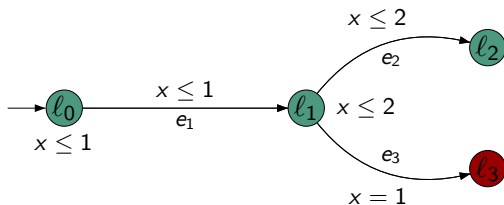
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 - ▶ instantaneous events
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$\mathcal{A} \not\models G \bullet$ but $\mathcal{A} \approx G \bullet$

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$$\mathcal{A} \not\models G \bullet \text{ but } \mathcal{A} \approx G \bullet$$

Aim: Relax the semantics of timed automata.

Big and small sets

Given \mathcal{A} and φ , we want to define $\mathcal{A} \models \varphi$ s.t.

$$\{\rho \mid \rho \not\models \varphi\} \lll \{\rho \mid \rho \models \varphi\}$$

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Topology	$\{\rho \mid \rho \not\models \varphi\}$ is meager	$\{\rho \mid \rho \models \varphi\}$ is large
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Banach-Mazur games relate the two notions in the framework of finite systems [VV06]

Outline

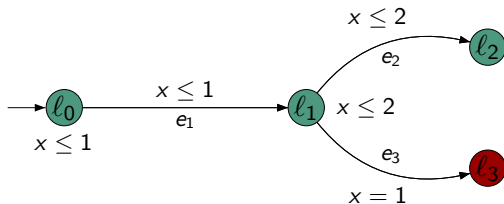
- 1 Introduction
- 2 Probabilistic semantics and almost-sure model-checking
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Symbolic paths

Symbolic path

A timed-automaton, s state and $e_1 \cdots e_n$ edges

$$\pi(s \xrightarrow{e_1} \cdots \xrightarrow{e_n}) = \{\rho = s \xrightarrow{\tau_1, e_1} \cdots \xrightarrow{\tau_n, e_n} s_n \mid \rho \text{ run of } \mathcal{A}\}$$



$$\pi((l_0, 0), e_1 e_2) = \{(l_0, 0) \xrightarrow{\tau_1, e_1} s_1 \xrightarrow{\tau_2, e_2} s_2 \mid 0 \leq \tau_1 \leq 1; 0 \leq \tau_1 + \tau_2 \leq 2\}$$

Probabilistic semantics

- Intuitively:** From state s ,
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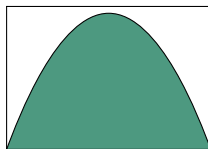
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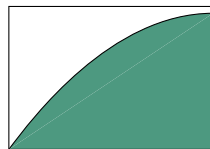
Examples of μ_s when $I(s)$ is a bounded interval



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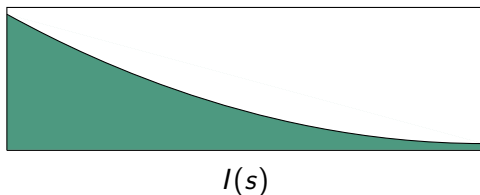
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Example of μ_s when $I(s)$ is unbounded



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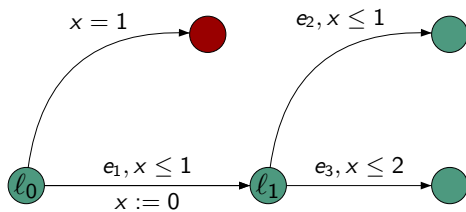
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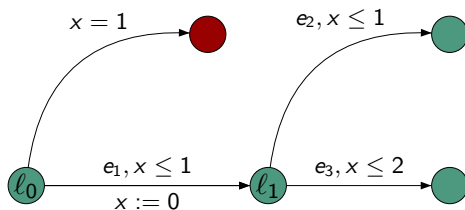
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- ▶ $s \xrightarrow{t, e_1} s_t$

Example of probability computation



Example of probability computation



$$\mathbb{P}(\pi((l_0, 0), e_1 e_2)) = \frac{1}{4}$$

$$\begin{aligned} \mathbb{P}(\pi((l_0, 0), e_1 e_2)) &= \int_{t=0}^1 \mathbb{P}(\pi((l_1, 0), e_2)) d\mu_{(l_0, 0)}(t) \\ &= \int_{t=0}^1 \int_{u=0}^1 \frac{1}{2} d\mu_{(l_1, 0)}(u) dt \\ &= \int_{t=0}^1 \int_{u=0}^1 \frac{1}{2} \frac{du}{2} dt = \frac{1}{4} \end{aligned}$$

Probabilistic semantics (infinite runs)

Cylinder generated by π : $\text{Cyl}(\pi) = \{\rho_1 \cdot \rho_2 \mid \rho_1 \in \pi\}$

- ▶ $\mathbb{P}(\text{Cyl}(\pi)) = \mathbb{P}(\pi)$
- ▶ extension of \mathbb{P} to the σ -algebra generated by all $\text{Cyl}(\pi)$

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Almost-sure model-checking of LTL

Let φ be an LTL formula.

$$\mathcal{A} \approx_{\mathbb{P}} \varphi \stackrel{\text{def}}{\iff} \mathbb{P}(\{\rho \mid \rho \models \varphi\}) = 1$$

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A notion of dimension

Polyedron associated with a symbolic path $\pi = \pi(s \xrightarrow{e_1} \dots \xrightarrow{e_n})$

$$\text{Pol}(\pi) = \{(\tau_1, \dots, \tau_n) \in (\mathbb{R}^+)^n \mid s \xrightarrow{\tau_1, e_1} s_1 \xrightarrow{\tau_2, e_2} \dots \xrightarrow{\tau_n, e_n} s_n\}$$

A notion of dimension

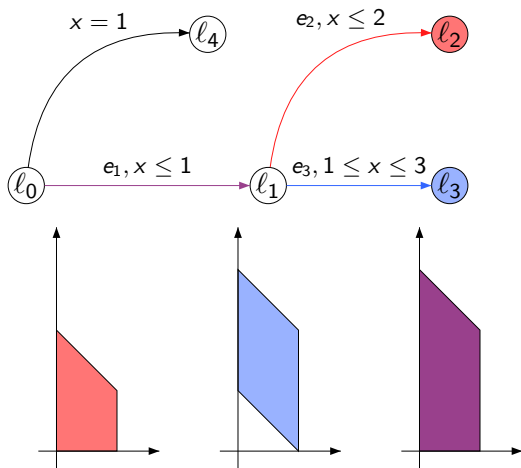
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Dimension of a symbolic path

$$\dim(\pi) = \top \stackrel{\text{def}}{\iff} \begin{array}{l} \blacktriangleright \dim(\pi(s \xrightarrow{e_1} \dots \xrightarrow{e_{n-1}})) = \top, \text{ and} \\ \blacktriangleright \text{Pol}(\pi) \text{ is of maximal dimension in} \\ \bigcup_e \text{Pol}(\pi(s \xrightarrow{e_1} \dots \xrightarrow{e_{n-1}} \xrightarrow{e})) \end{array}$$

Dimension on an example

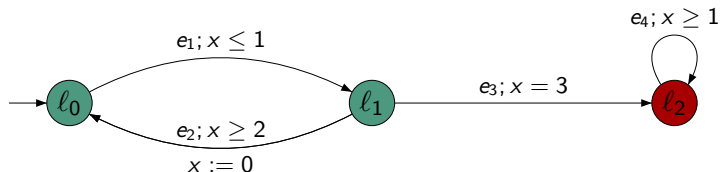


$\text{Pol}(\pi((l_0, 0), e_1 e_2))$ is of max. dim. in $\text{Pol}(\pi((l_0, 0), e_1 \cdot))$
 $\dim(\pi((l_0, 0), e_1 e_2)) = \top$ $\dim(\pi((l_0, 0), e_1 e_3)) = \top$

Topology on runs

Topology $T_{\mathcal{A}}$ on $\text{Runs}(\mathcal{A}, s)$

Basic open sets of $T_{\mathcal{A}}$ are $\text{Cyl}(\pi)$ of defined dimension



From $s_0 = (l_0, 0)$, basic open sets are

$$\text{Cyl}(\pi(s, (e_1 e_2)^*)) \quad \text{Cyl}(\pi(s, e_1 (e_2 e_1)^*))$$

Meager and large sets

A set of runs X is **nowhere dense** if $\overset{\circ}{\bar{X}} = \emptyset$.

X is **meager** if it is a countable union of nowhere dense sets

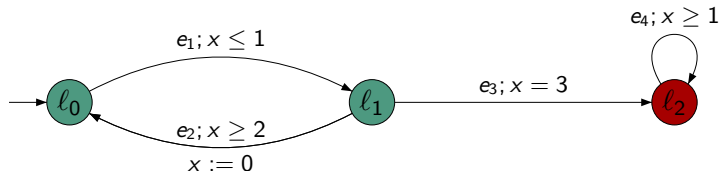
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- ▶ $\pi(s_0, e_1 e_3 e_4)$ is nowhere dense
- ▶ $\{\pi(s_0, (e_1 e_2)^* e_1 e_3 e_4^*)\}$ is meager
- ▶ $\{\pi(s_0, (e_1 e_2)^*)\} \cup \{\pi(s_0, e_1 (e_2 e_1)^*)\}$ is large

Large model-checking

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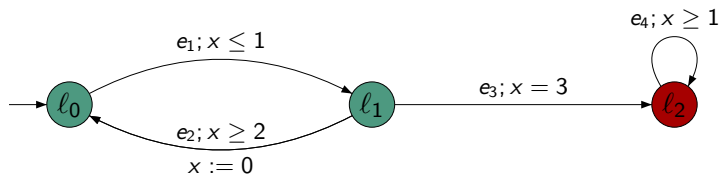
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$$\mathcal{A} \approx_T \mathbf{G} \bullet$$

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- ▶ and so on... $B_1 \supseteq B_2 \supseteq B_3 \supseteq B_4 \supseteq B_5 \dots$

The play is winning for Player 1 whenever $\bigcap_{i=1}^n B_i \cap C \neq \emptyset$.
Otherwise Player 2 wins.

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Theorem [Oxtoby 57]

Player 2 has a winning strategy iff C is meager.

Let's play Banach-Mazur games!

- ▶ Classical topology on \mathbb{R} ,
 $\mathcal{B} = \{(r, r') \mid r \neq r' \in \mathbb{Q}\}$,
 $\mathcal{C} = (0, 1)$.
→ Player 1 can always choose B_{2i+1} included in a closed sub-interval of B_{2i}
Player 1 wins the game, hence $(0, 1)$ is not meager.

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- ▶ Topology on \mathbb{R} induced by $\{(0, a) \mid 0 < a \leq 1\}$,
 $\mathcal{B} = \{(0, a) \mid 0 < a \leq 1\}$,
 $\mathcal{C} = (0, 1)$.
 → Player 2 can choose a subsequence of $(0, 1/2^i)$
 Player 2 has a winning strategy, hence $(0, 1)$ is meager.

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Case of finite paths: Perfect match

Theorem

Let \mathcal{A} be a timed automaton and $R(\mathcal{A})$ its region graph.

$$\mathcal{A}, s \models_{\mathbb{P}} \varphi \quad \Leftrightarrow \quad \mathcal{A}, s \models_{\mathcal{T}} \varphi$$

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Characterization:

$$\mathcal{A}, s \models \varphi \Leftrightarrow \forall \pi (\pi \not\models \varphi) \Rightarrow \dim(\pi) = \perp.$$

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Theorem

Over finite timed words, the almost sure and large model-checking problems for LTL are PSPACE-Complete.

Extension to infinite paths

Naiv extension:

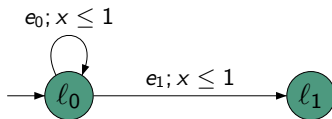
$$\mathbb{P}(s \models \varphi) = 1 \quad \Leftrightarrow \quad \forall \pi (\pi \not\models \varphi) \Rightarrow \dim(\pi) = \perp.$$

Extension to infinite paths

Naiv extension:

$$\mathbb{P}(s \models \varphi) = 1 \iff \forall \pi (\pi \not\models \varphi \Rightarrow \dim(\pi) = \perp).$$

Hopeless



$\mathbb{P}(s_0 \models \mathbf{F} l_1) = 1$ but $\pi(s_0, e_0^\omega) \not\models \varphi$ and $\dim(\pi(s_0, e_0^\omega)) = \top$.
 → Need for fairness

Second attempt

Fair extension:

$$\mathbb{P}(s \models \varphi) = 1 \Leftrightarrow \forall \pi (\pi \text{ is fair} \wedge \pi \not\models \varphi) \Rightarrow \dim(\pi) = \perp.$$

Fair path

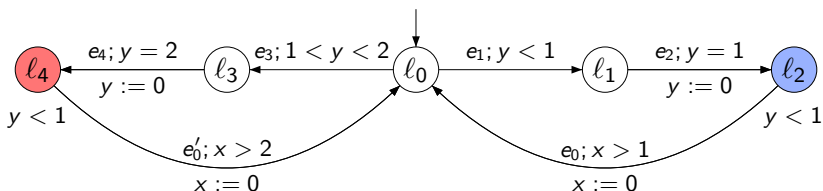
$\pi(s, e_1 \cdots e_n)$ is *fair* if any transition with define dimension enabled infinitely often along π is taken infinitely often.

Second attempt

Fair extension:

$$\mathbb{P}(s \models \varphi) = 1 \Leftrightarrow \forall \pi (\pi \text{ is fair} \wedge \pi \not\models \varphi) \Rightarrow \dim(\pi) = \perp.$$

Hopeless $\varphi = \mathbf{GF} \ell_4 \wedge \mathbf{GF} \ell_2$



$\pi \text{ fair} \Rightarrow \pi \models \varphi$

Hence $\forall \pi (\pi \text{ is fair} \wedge \pi \not\models \varphi) \Rightarrow \dim(\pi) = \perp.$ **But** $\mathbb{P}(\varphi) < 1.$

→ Restriction on the number of clocks

Results

A **single-clock** timed automaton

Theorem

Let s be a state of \mathcal{A} and φ and LTL formula.

$$\begin{aligned} \mathbb{P}(s \models \varphi) = 1 &\Leftrightarrow \forall \pi (\pi \text{ is fair} \wedge \pi \not\models \varphi) \Rightarrow \text{dim}(\pi) = \perp \\ &\Leftrightarrow \{\pi \mid \pi \text{ is fair} \wedge \pi \models \varphi\} \text{ is large} \end{aligned}$$

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Characterization: BSCC of $R(\mathcal{A})$

Theorem

The almost sure model-checking problem of LTL for single-clock timed automata is PSPACE-Complete.

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Related work

Robustness

- ▶ robust timed automata [GHJ97,HR00]
- ▶ robust model-checking [Puri98,DDR04,DDMR04,ALM05,BMR06,BMR08]

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Probabilistic timed models

- ▶ probabilistic timed automata *à la* PRISM [KNSS02]
- ▶ real-time probabilistic systems [ACD91,ACD92]
- ▶ continuous-time Markov chains [BHHK03]

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Summary

- ▶ probabilistic semantics for timed automata to rule out unlikely events
- ▶ equivalent topological semantics
- ▶ decision algorithm for qualitative LTL almost-sure/fair model-checking
 - ▶ for finite runs
 - ▶ for infinite runs in one-clock timed automata

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On-going work

- ▶ quantitative model-checking
- ▶ verification of timed logics
- ▶ timed games with a probabilistic semantics