

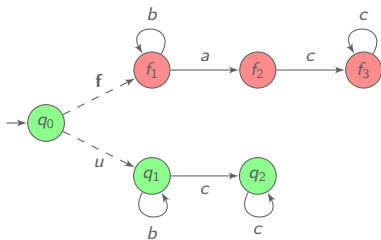
Fault diagnosis for Probabilistic Systems

Nathalie Bertrand

Inria Rennes, France

based on joint work with Éric Fabre, Stefan Haar, Serge Haddad,
Loïc Hélouët and Engel Lefaucheux

Objective: tell whether a fault occurred, based on observations.

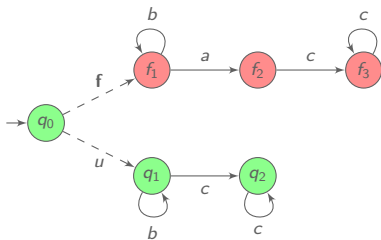


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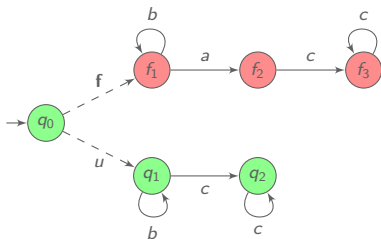
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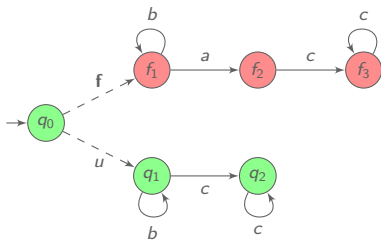
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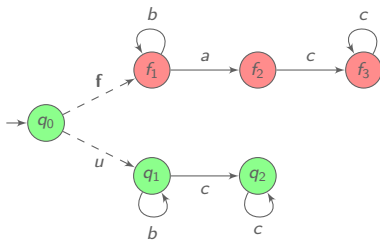
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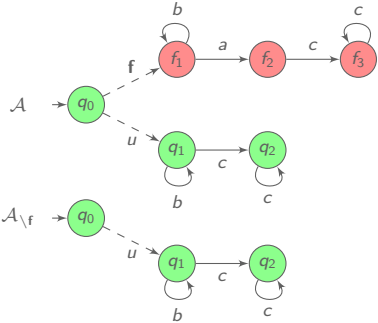
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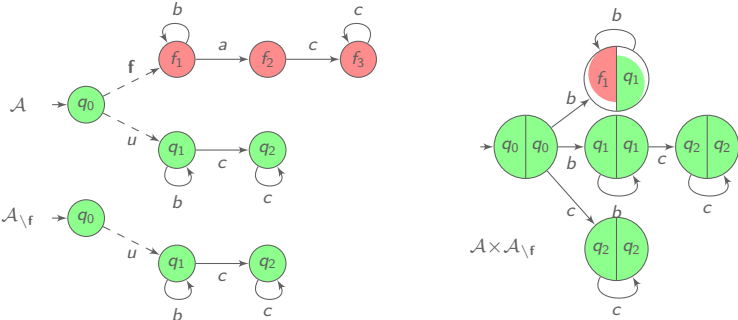
Remark: w.l.o.g. state space partitionned into correct and faulty states

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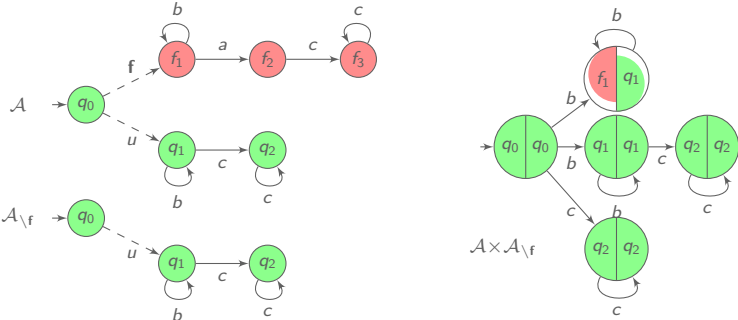
Deciding diagnosability in discrete event systems



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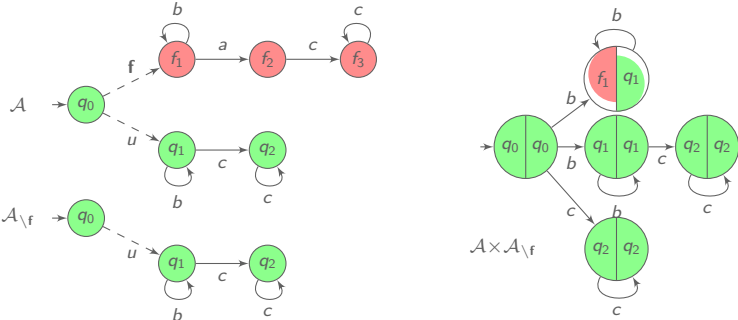
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indeterminate cycle: $(f_0, q_0) \cdots \rightarrow (f_n, q_n) \rightarrow (f_0, q_0)$ s.t. f_i **faulty** and q_i **correct**

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Decidability and complexity of diagnosability [JHCK01]
Diagnosability is decidable in PTIME.

Diagnosers

Diagnoser: assigns verdicts to observed sequences $D : \Sigma_o^* \rightarrow \{\checkmark, \times, ?\}$

Diagnoser requirements

- ▶ **Soundness:** if a fault is claimed, a fault occurred.
- ▶ **Reactivity:** every fault is eventually detected.

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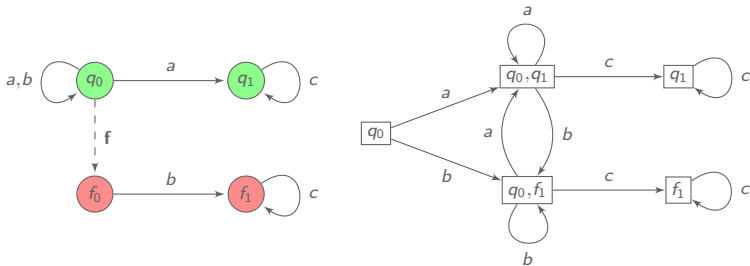
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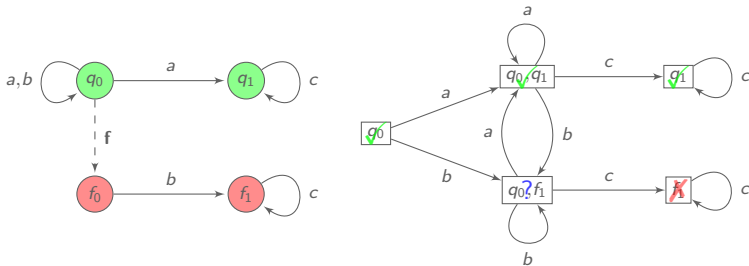
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Diagnoser synthesis

Complexity of diagnoser synthesis

[JHCK01]

Diagnoser synthesis is in EXPTIME.

intuition: subset construction to track possible correct and faulty states

Diagnoser synthesis

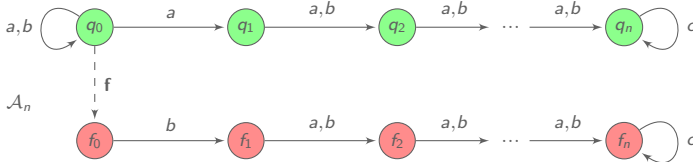
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There is a family (\mathcal{A}_n) of diagnosable systems such that \mathcal{A}_n has $2n + 2$ states and any diagnoser needs 2^n states.



diagnoser must remember the last n events: 2^n possibilities

[JHCK01] Jiang, Huang, Chandra and Kumar, *A polynomial algorithm for testing diagnosability of discrete-event systems*, TAC, 2001.

Outline

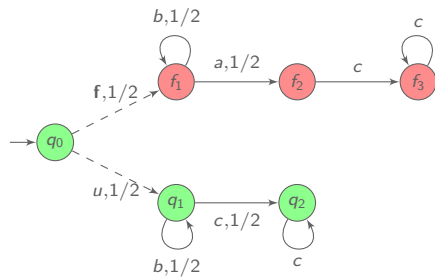
Introduction to fault diagnosis

Diagnosability in probabilistic systems

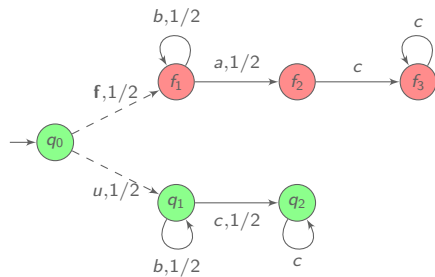
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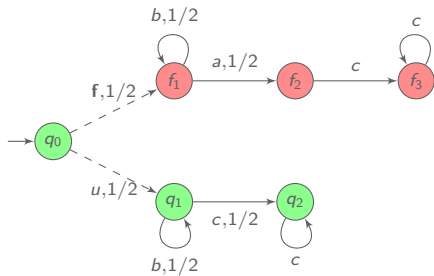


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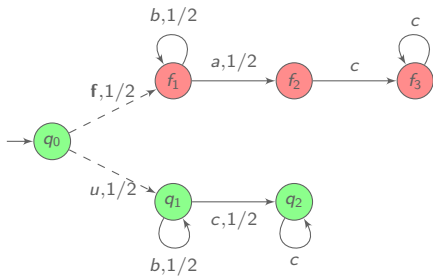
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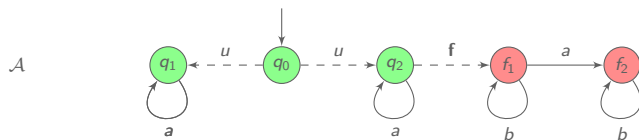
Diagnosability: Probability of infinite ambiguous sequences is zero.

[TT05] Thorsley and Teneketzis, *Diagnosability of stochastic discrete-event systems*, TAC, 2005.

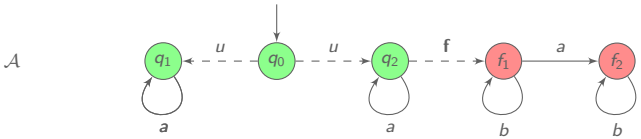
[CK13] Chen and Kumar, *Polynomial test for stochastic diagnosability of discrete-event systems*, TASE, 2013.

[BHL14] B., Haddad and Lefauchaux, *Foundation of diagnosis and predictability in probabilistic systems*, FSTTCS'14.

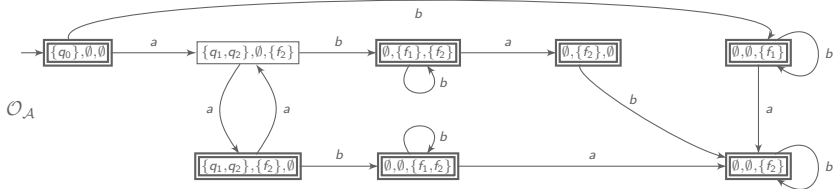
Characterisation of diagnosability



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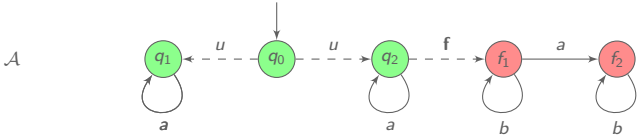


deterministic Büchi automaton $\mathcal{O}_{\mathcal{A}}$ characterizes non-ambiguous sequences

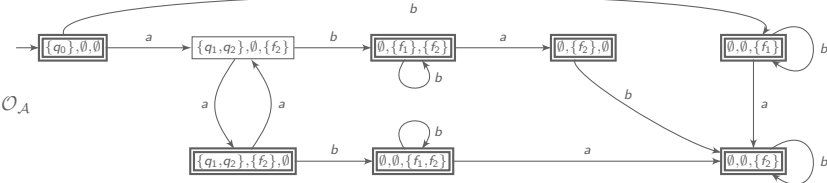


states (U, V, W) with U possible correct states; V waiting room for possible faulty states; W possible faulty states for latest faults [HHMS13]

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states (U, V, W) with U possible correct states; V waiting room for possible faulty states; W possible faulty states for latest faults [HHMS13]

\mathcal{A} is not diagnosable iff
 there exists a BSCC of $\mathcal{A} \times \mathcal{O}_{\mathcal{A}}$ where every state (q, U, V, W) satisfies
 q faulty and $U \neq \emptyset$ or q correct and $W \neq \emptyset$.

Complexity of diagnosability

Diagnosability is in PSPACE for probabilistic systems.

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NFA \mathcal{A} is **eventually universal** if there exists w such that $w\Sigma^* \subseteq \mathcal{L}(\mathcal{A})$.

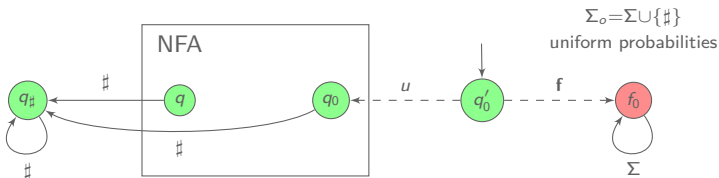
The eventual universality problem for live NFA
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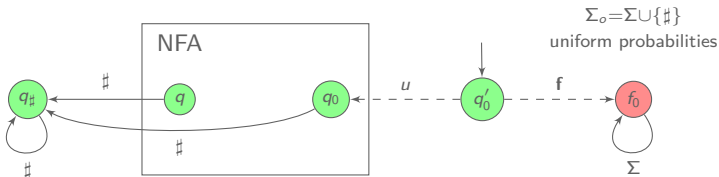


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Diagnosability is PSPACE-complete for probabilistic systems. [BHL14]

[BHL14] B., Haddad and Lefauchaux, *Foundation of diagnosis and predictability in probabilistic systems*, FSTTCS'14.

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For every diagnosable system with n correct states
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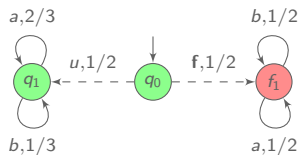
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Diagnoser derived from observer $\mathcal{O}_{\mathcal{A}}$: \times in states (\emptyset, V, W)
 \checkmark in states (U, V, \emptyset) with $U \neq \emptyset$
 $?$ otherwise.

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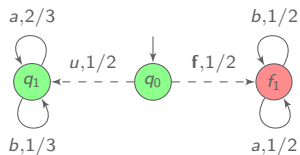
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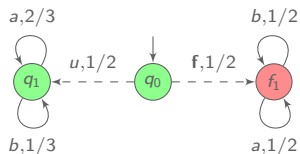
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Active diagnosis

Objective: control the system so that it is diagnosable

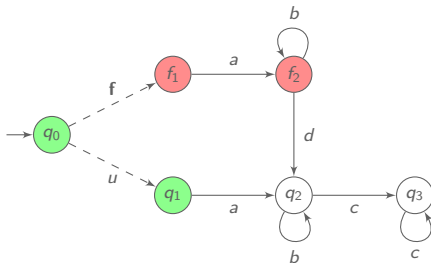
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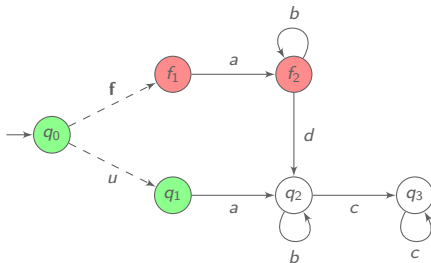
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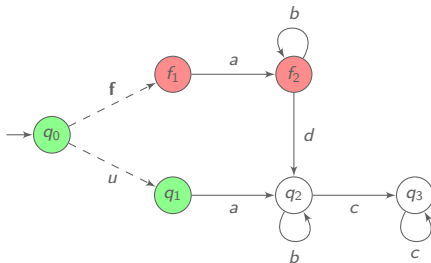
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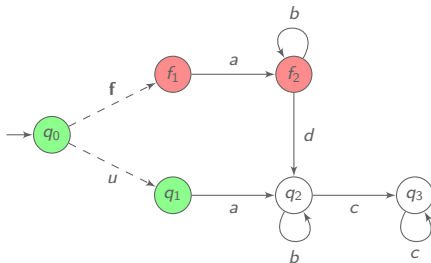
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$$\sigma : \Sigma_o^* \rightarrow 2^{\Sigma_c}$$

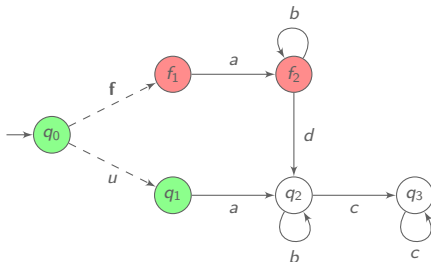
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Active diagnosis problem

does there exist a controller such that the system is diagnosable?

caution: the system must remain *live*.

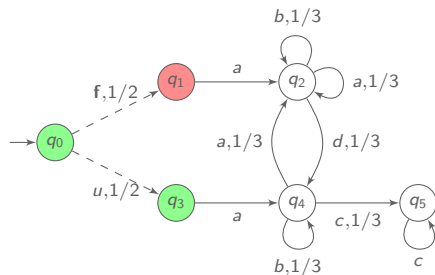
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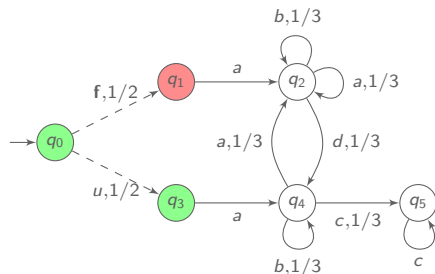
Active probabilistic diagnosis

Objective: control the system so that it is almost-surely diagnosable



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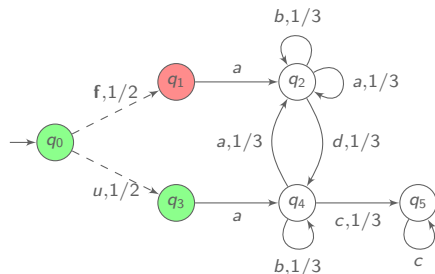
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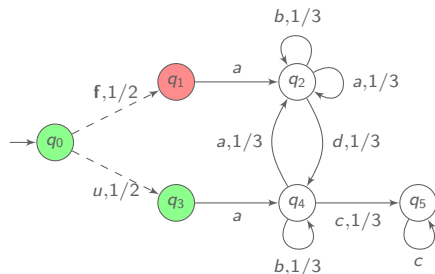


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Controller $\sigma : \Sigma_o^* \rightarrow \text{Dist}(2^{\Sigma_c})$

Active probabilistic diagnosis problem

[BFHHH14]

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[BFHHH14] B., Fabre, Haar, Haddad and Hélouët, *Active diagnosis for probabilistic systems*, FoSSaCS'14.

Solving active probabilistic diagnosis

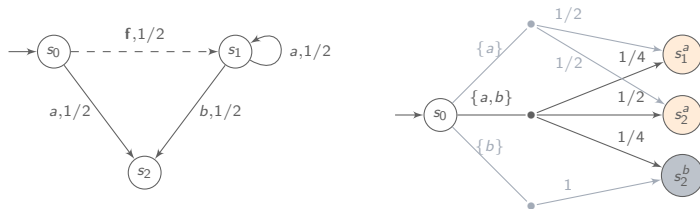
The active probabilistic diagnosis problem is **EXPTIME-complete**.

Solving active probabilistic diagnosis

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Proof idea (upper bound)

- ▶ characterize unambiguous sequences by deterministic Büchi automaton \mathcal{B} [HHMS13]
- ▶ build the product of probabilistic LTS with \mathcal{B}
- ▶ view it as POMDP \mathcal{P}



- ▶ decide whether there is an almost-surely winning strategy for the Büchi condition on \mathcal{P} [BBG08, CDGH10]

[HHMS13] Haar, Haddad, Melliti and Schwoon, *Optimal constructions for active diagnosis*, FSTTCS'13.

[BBG08] Baier, B. and Größer, *On decision problems for probabilistic Büchi automata*, FoSSaCS'08.

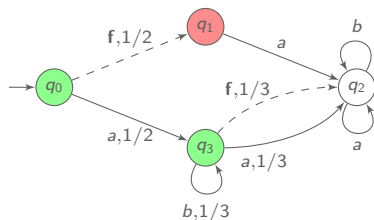
[CDGH10] Chatterjee, Doyen, Gimbert and Henzinger, *Randomness for free*, MFCS'10.

Safe active probabilistic diagnosis

Objective: avoid fault-provocative controllers

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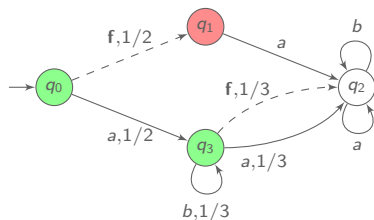
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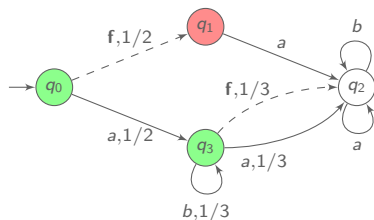
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[BFHHH14]

does there exist a controller such that the system is almost-surely diagnosable **and** correct runs have positive probability?

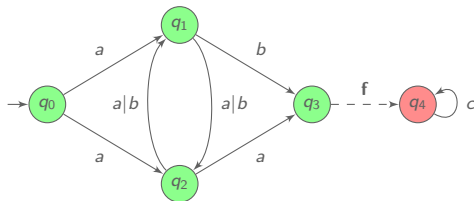
[BFHHH14] B., Fabre, Haar, Haddad and H elou et, *Active diagnosis for probabilistic systems*, FoSSaCS'14.

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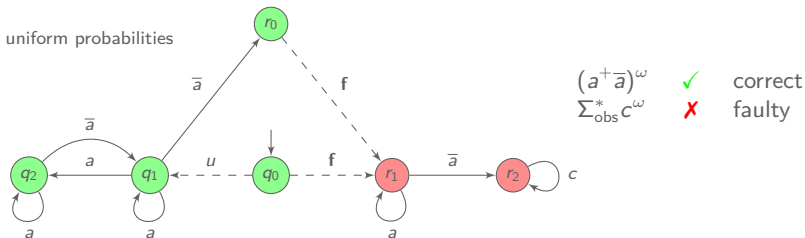


Finite-memory is not enough!

Infinite memory is needed for safe probabilistic diagnosis.

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Infinite memory is needed for safe probabilistic diagnosis.



- ▶ Safe controller: infinitely many \bar{a} 's to diagnose all faults...
but not too often, to have non-negligible correct runs
- ▶ Finite-memory controllers almost-surely force a fault.

Solving safe active probabilistic diagnosis?

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The safe active probabilistic diagnosis problem restricted to **finite memory strategies** is **EXPTIME-complete**.

Outline

Introduction to fault diagnosis

Diagnosability in probabilistic systems

Control for probabilistic diagnosability

Conclusion

Concluding remarks

Contributions: Foundations of stochastic diagnosis

- ▶ Investigation of semantical issues
- ▶ Tight complexity bounds for diagnosability and diagnoser synthesis problems
- ▶ Active diagnosability: controller synthesis to ensure diagnosability

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Perspectives: Towards more quantitative questions

- ▶ Bounded-delay diagnosis
tradeoff: delay vs diagnosability probability
- ▶ Space and time optimisation of observations
tradeoff: observation cost vs diagnosability probability
- ▶ Active approximate diagnosis